

Prompting in Visual Generation

Ziwei Liu

Nanyang Technological University

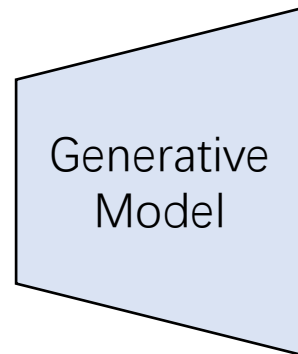
Prompting in Generation



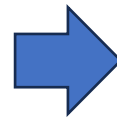
Image Prompt

"A Corgi"

Text Prompt



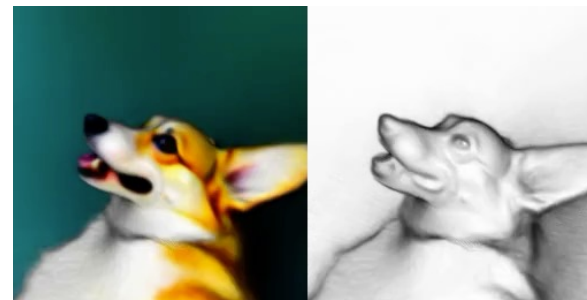
Generative
Model



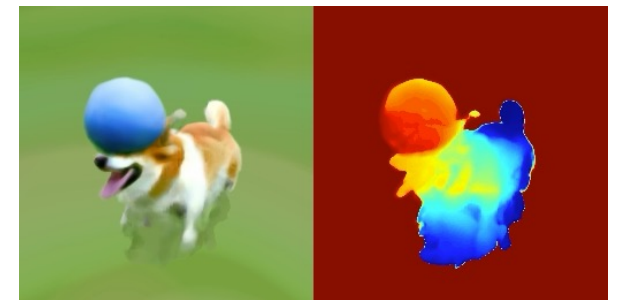
Image



Video



3D



4D Dynamic Scene

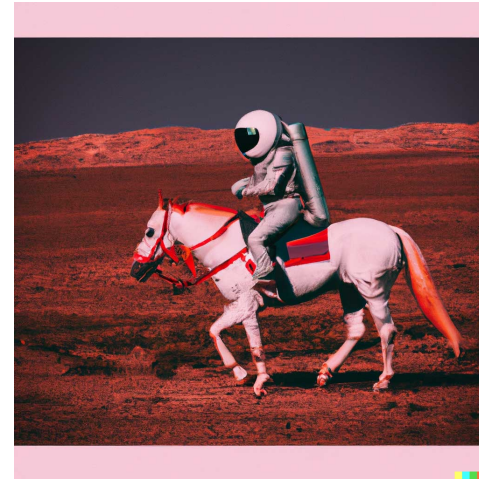


Text to Image Generation

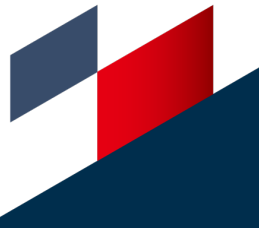


Text to Image Generation

- Prompt: An astronaut riding a horse in photorealistic style.



Source: <https://openai.com/dall-e-2>



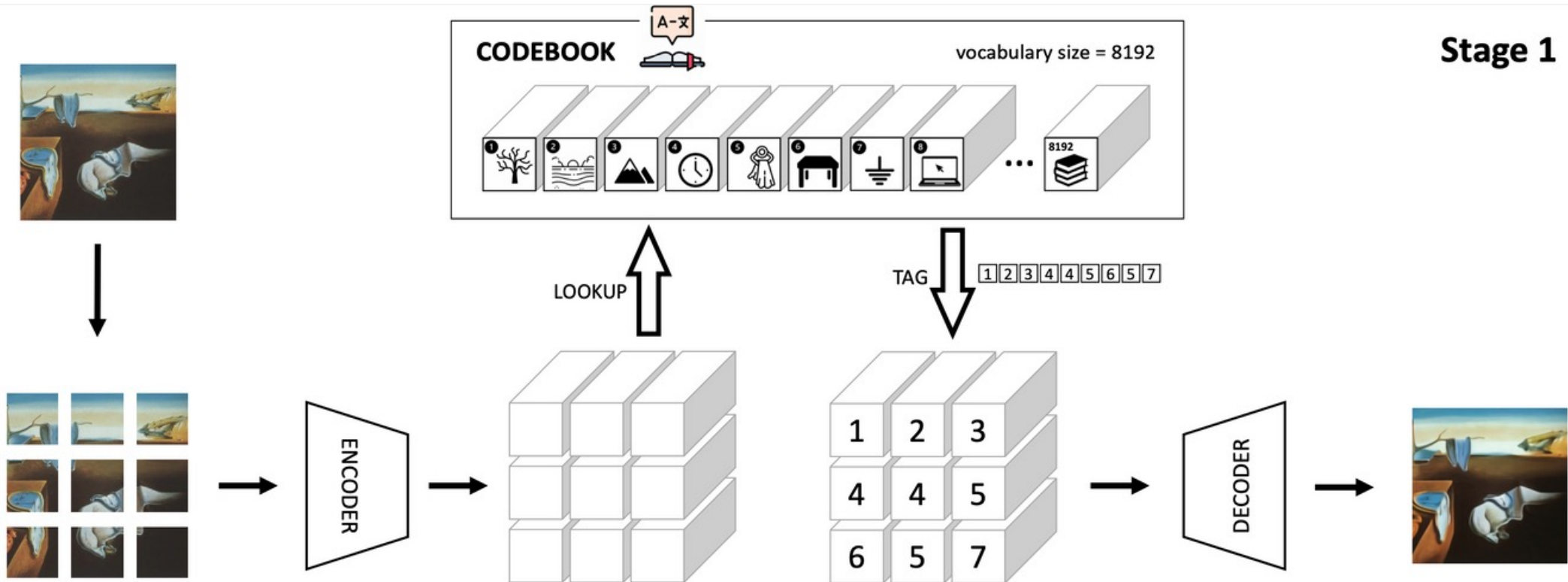
Text to Image Generation

- VQGAN-based Methods
 - DALLE
- Diffusion-based Methods
 - GLIDE, DALEE2, Stable Diffusion
- GAN-based Methods
 - GigaGAN
- Generation on Specialized data
 - Text2Human



DALLE

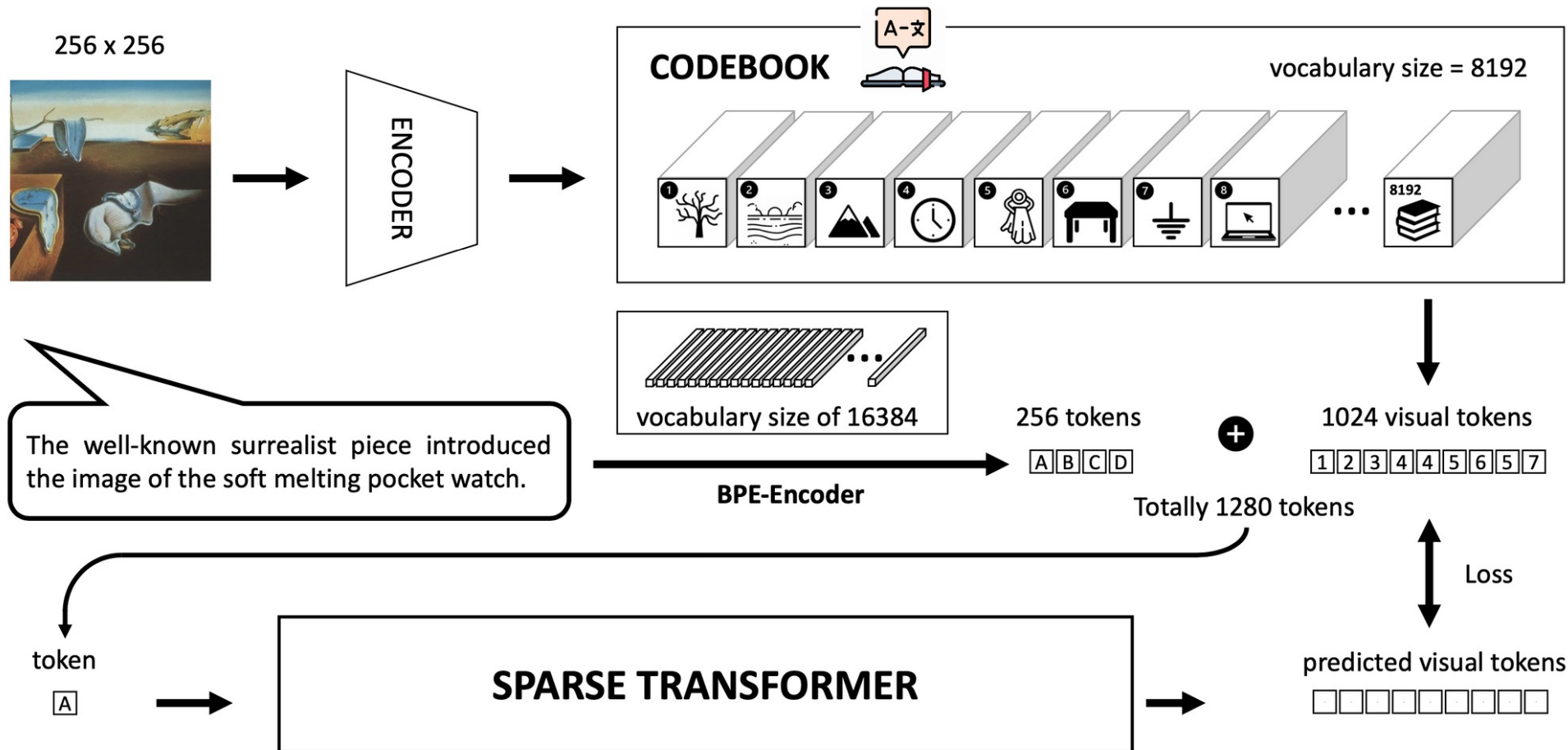
- Stage 1: Learning the Visual Codebook



Stage 1

DALLE

- Stage 2: Learning the Prior



GLIDE

- Diffusion Models

- Markov chain of latent variables by progressively adding Gaussian noise to samples

$$q(x_t|x_{t-1}) := \mathcal{N}(x_t; \sqrt{\alpha_t}x_{t-1}, (1 - \alpha_t)\mathcal{I})$$

- Learn a model to approximate the true posterior

$$p_\theta(x_{t-1}|x_t) := \mathcal{N}(\mu_\theta(x_t), \Sigma_\theta(x_t))$$

- The model is trained to predict the added noise

$$L_{\text{simple}} := E_{t \sim [1, T], x_0 \sim q(x_0), \epsilon \sim \mathcal{N}(0, \mathbf{I})} [\|\epsilon - \epsilon_\theta(x_t, t)\|^2]$$

- Guided Diffusion

$$\hat{\mu}_\theta(x_t|y) = \mu_\theta(x_t|y) + s \cdot \Sigma_\theta(x_t|y) \nabla_{x_t} \log p_\phi(y|x_t)$$



GLIDE

- Classifier-free guidance

$$\hat{\epsilon}_{\theta}(x_t|y) = \epsilon_{\theta}(x_t|\emptyset) + s \cdot (\epsilon_{\theta}(x_t|y) - \epsilon_{\theta}(x_t|\emptyset))$$

- CLIP Guidance

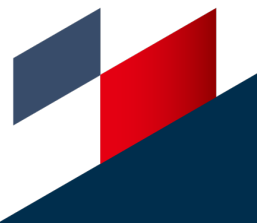
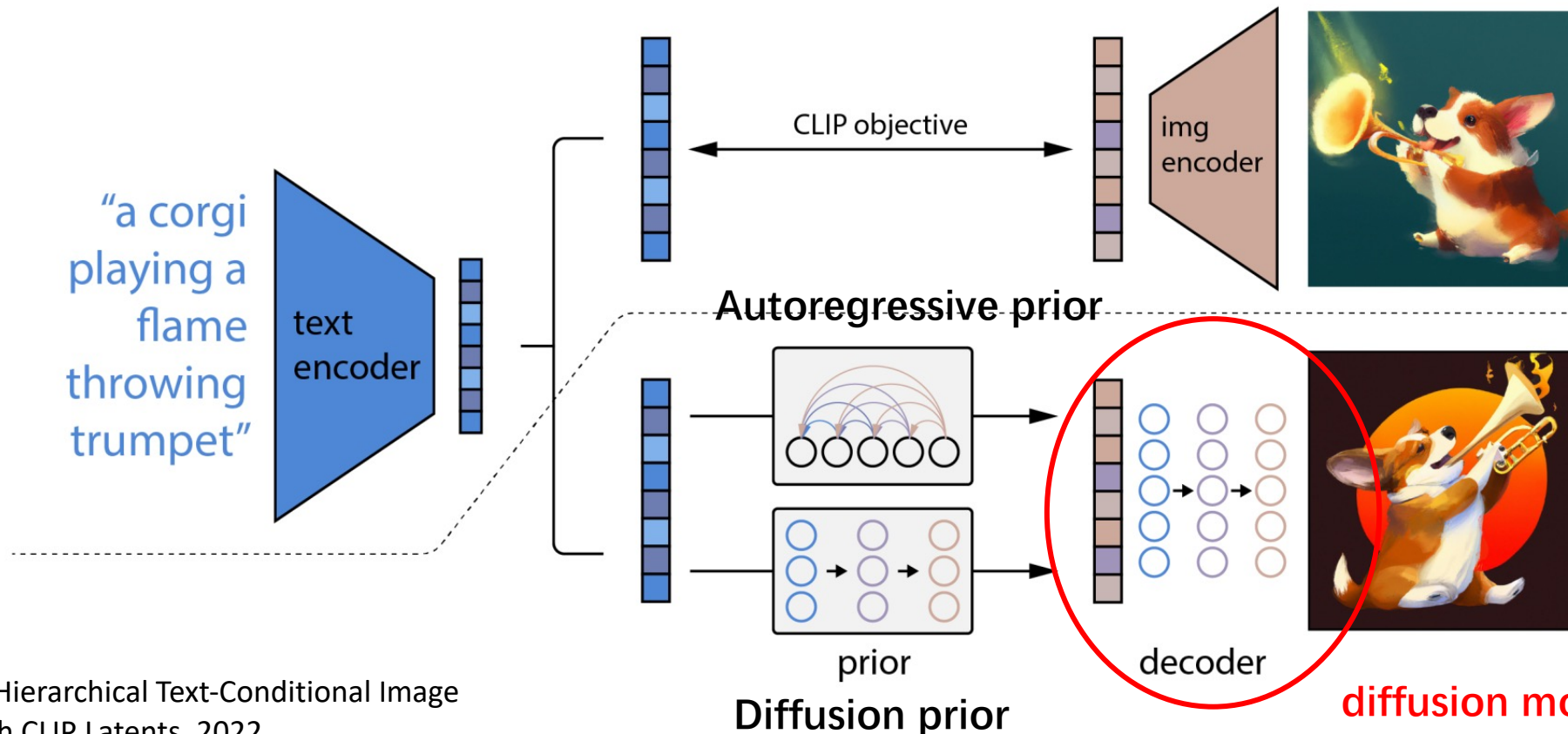
$$\hat{\mu}_{\theta}(x_t|c) = \mu_{\theta}(x_t|c) + s \cdot \Sigma_{\theta}(x_t|c) \nabla_{x_t} (f(x_t) \cdot g(c))$$

- Conclusion: Classifier-free guidance is preferred by human evaluators for both photorealism and caption similarity



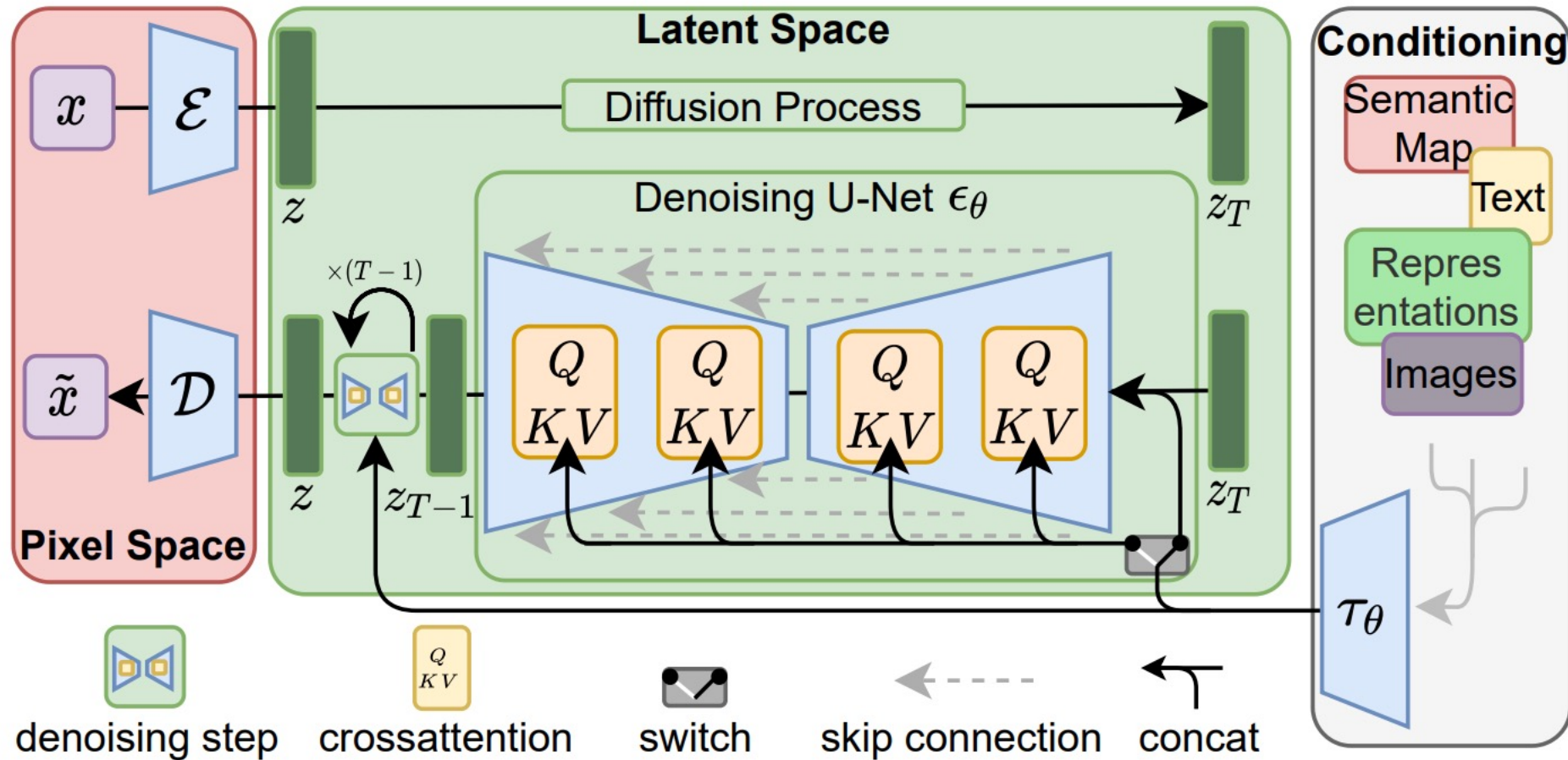
DALLE2

- Two key components:
 - Prior: produces CLIP Image Embeddings conditioned on captions
 - Decoder: produces images conditioned on CLIP Image Embeddings

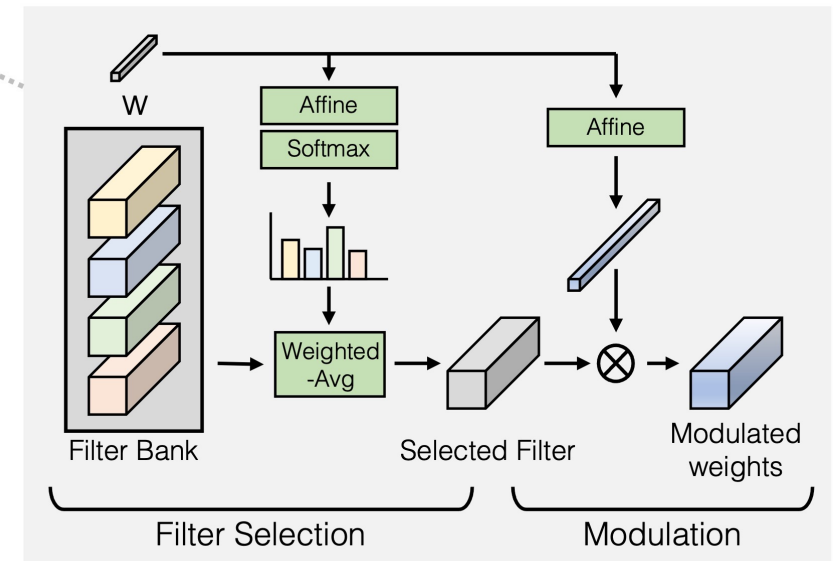
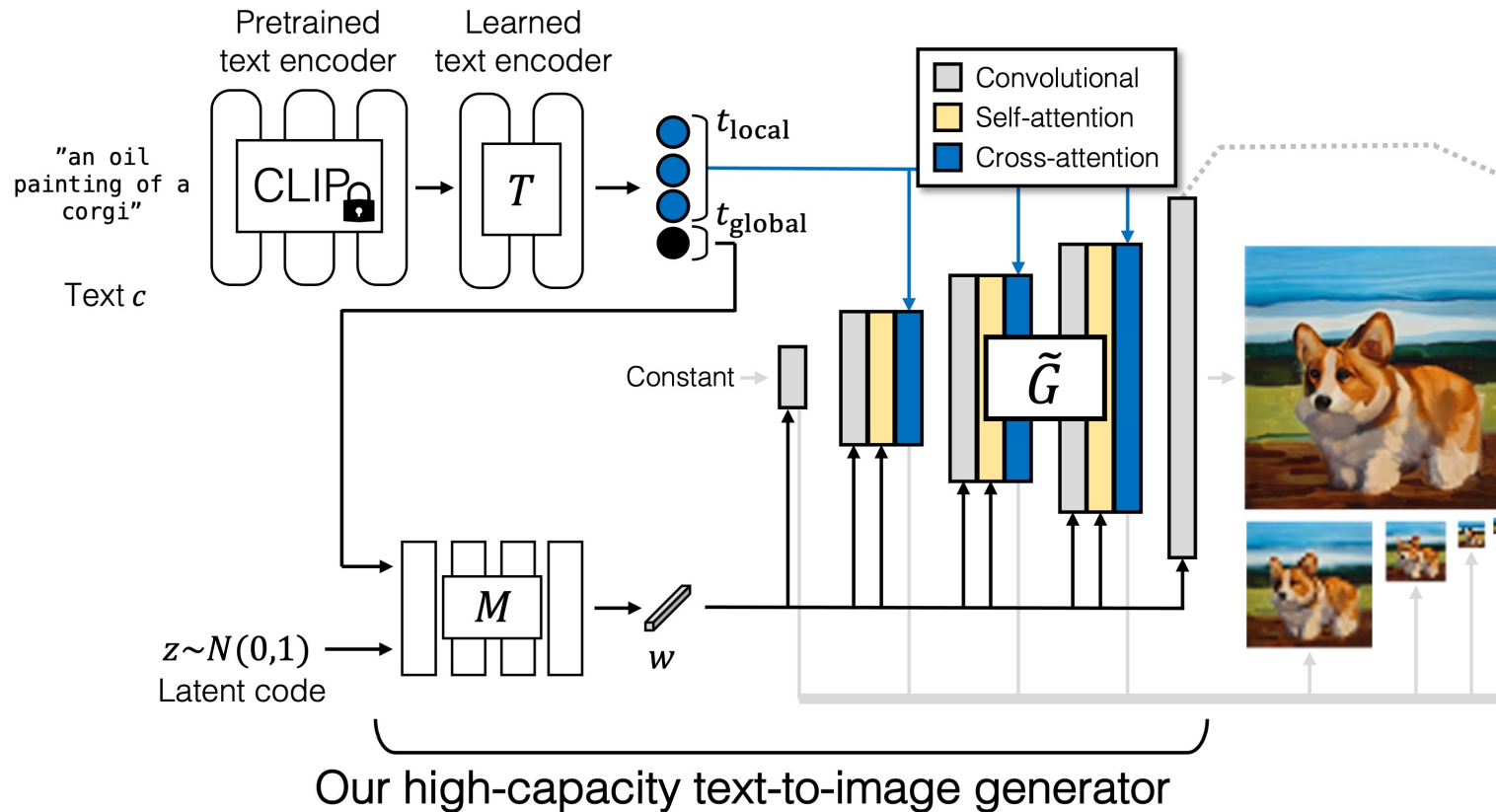


Stable Diffusion

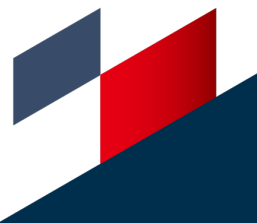
- Encode the images into the latent space



GigaGAN



Sample-adaptive kernel selection



Text2Human

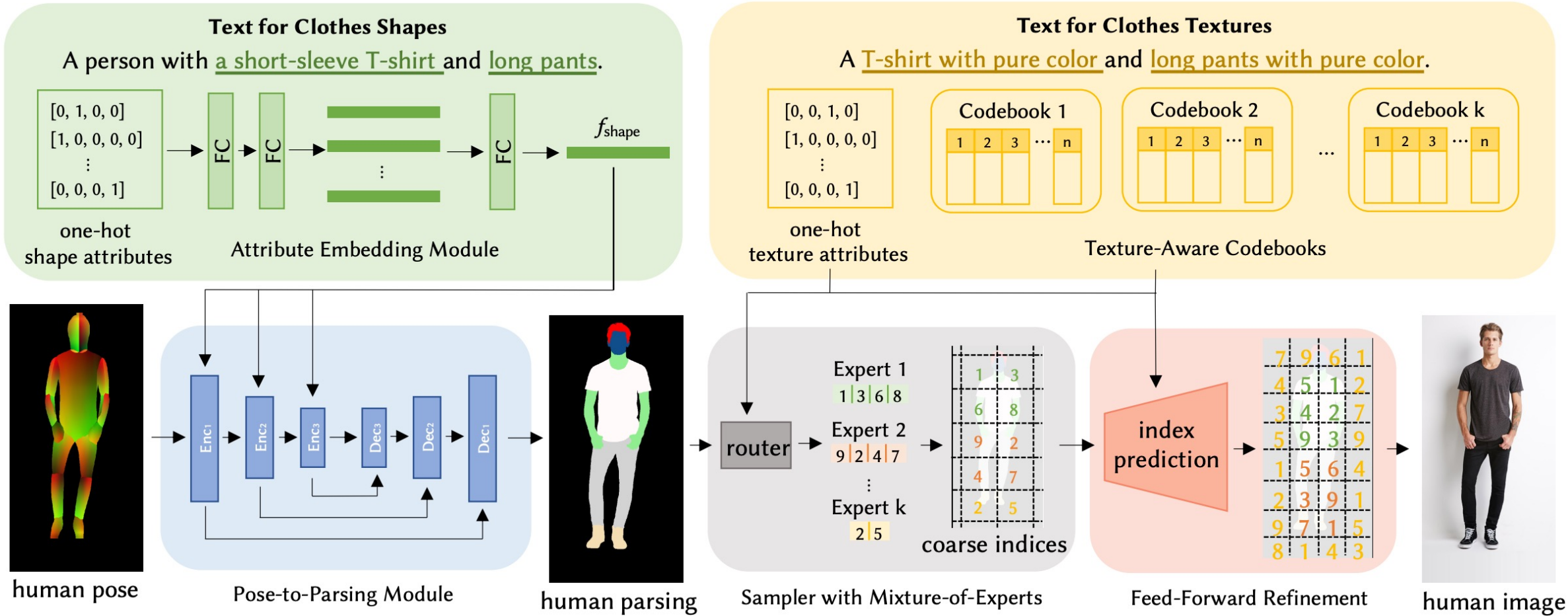


Image Prompt

- Prompting for Appearance Generation
 - Optimization-Based
 - Textual Inversion
 - DreamBooth
 - Encoder-Based
 - Tuning Encoder
 - ELITE
 - Taming Encoder
- Prompting for Relation Generation
 - ReVersion

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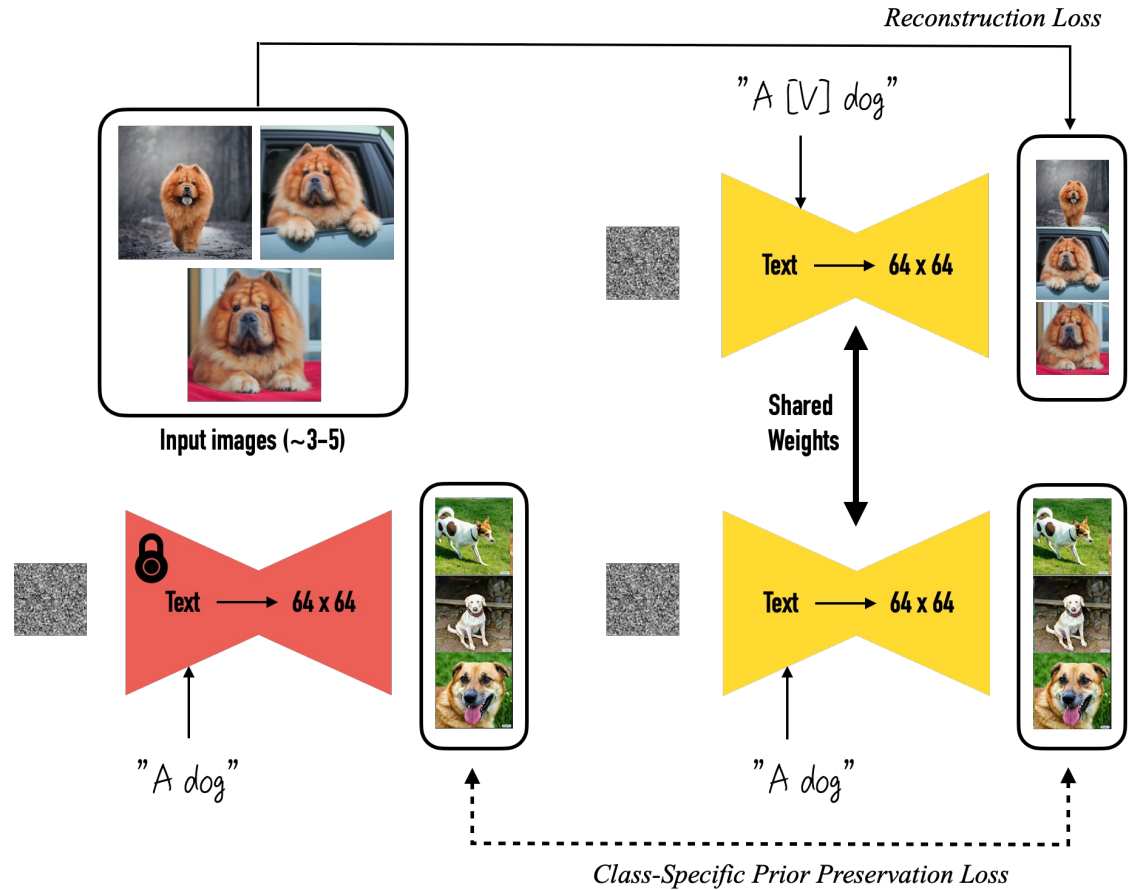
Textual Inversion



- Task: prompting for appearance generation (personalized generation)

- Method: optimize a text token: $v_* = \arg \min_v \mathbb{E}_{z \sim \mathcal{E}(x), y, \epsilon \sim \mathcal{N}(0,1), t} \left[\|\epsilon - \epsilon_\theta(z_t, t, c_\theta(y))\|_2^2 \right]$

DreamBooth



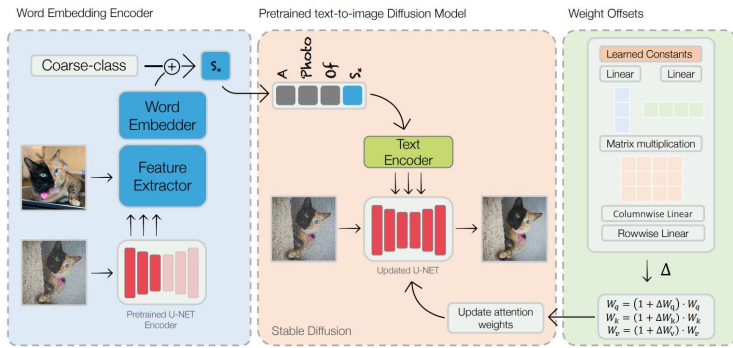
- Task: prompting for appearance generation (personalized generation)
- Method: fine-tune to obtain a personalized text-to-image model



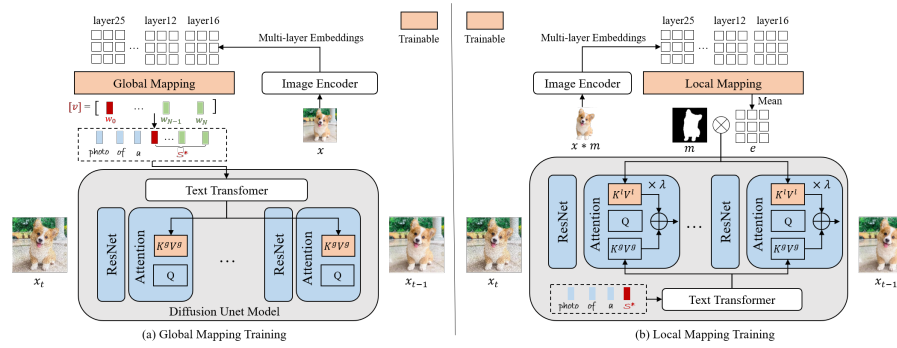
Image Prompt

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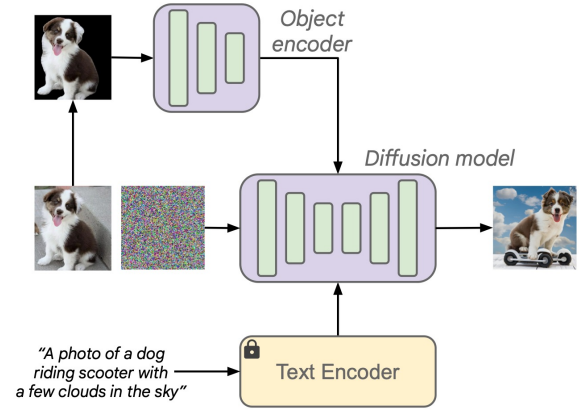
Encoder-Based



Tuning Encoder



ELITE



Taming Encoder

- Fast: a few optimization steps
- Memory Efficient
- One-Shot

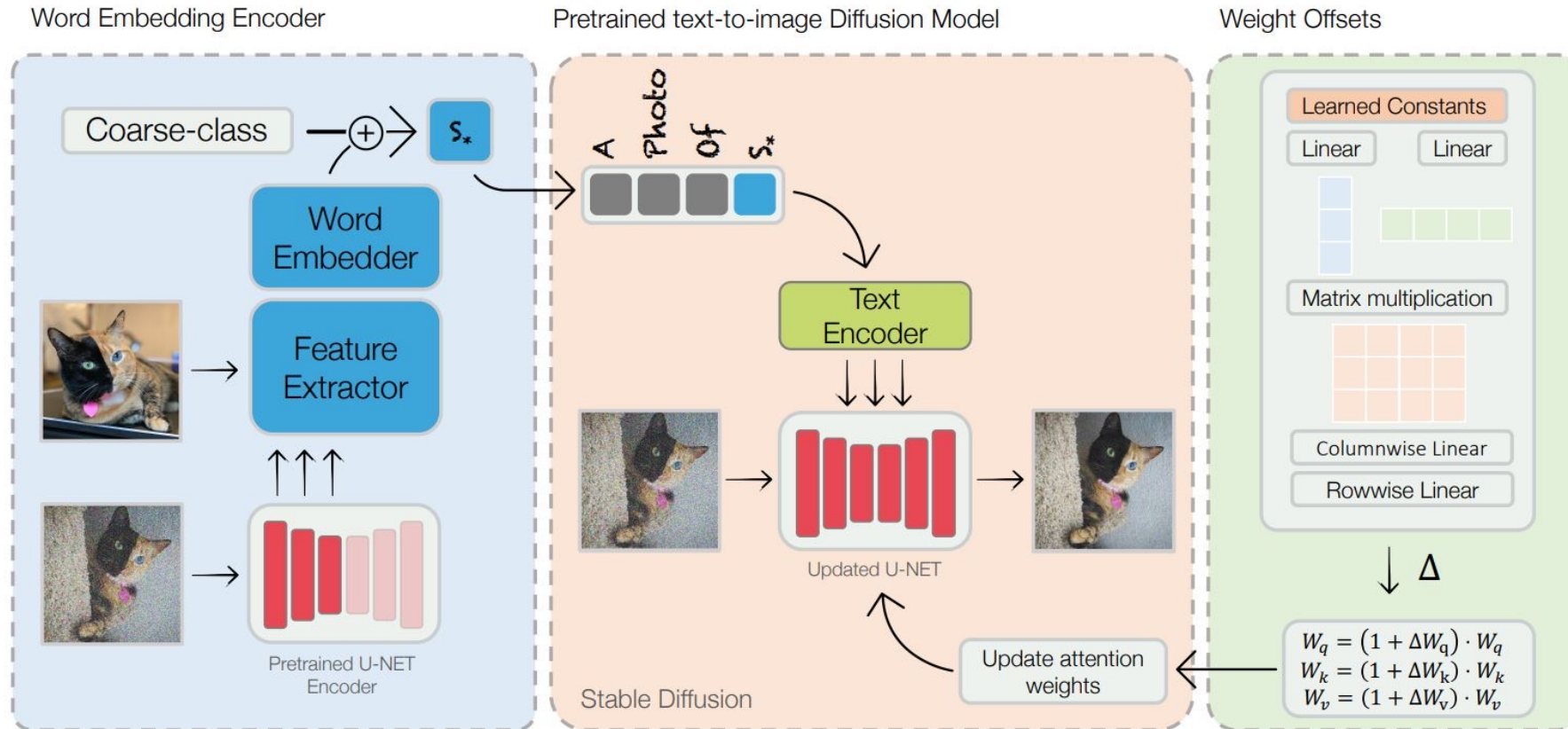
Encoder-based Domain Tuning for Fast Personalization of Text-to-Image Models (2023)

ELITE: Encoding Visual Concepts into Textual Embeddings for Customized Text-to-Image Generation (2023)

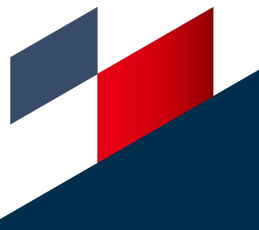
Taming encoder for zero fine-tuning image customization with text-to-image diffusion models (2023)



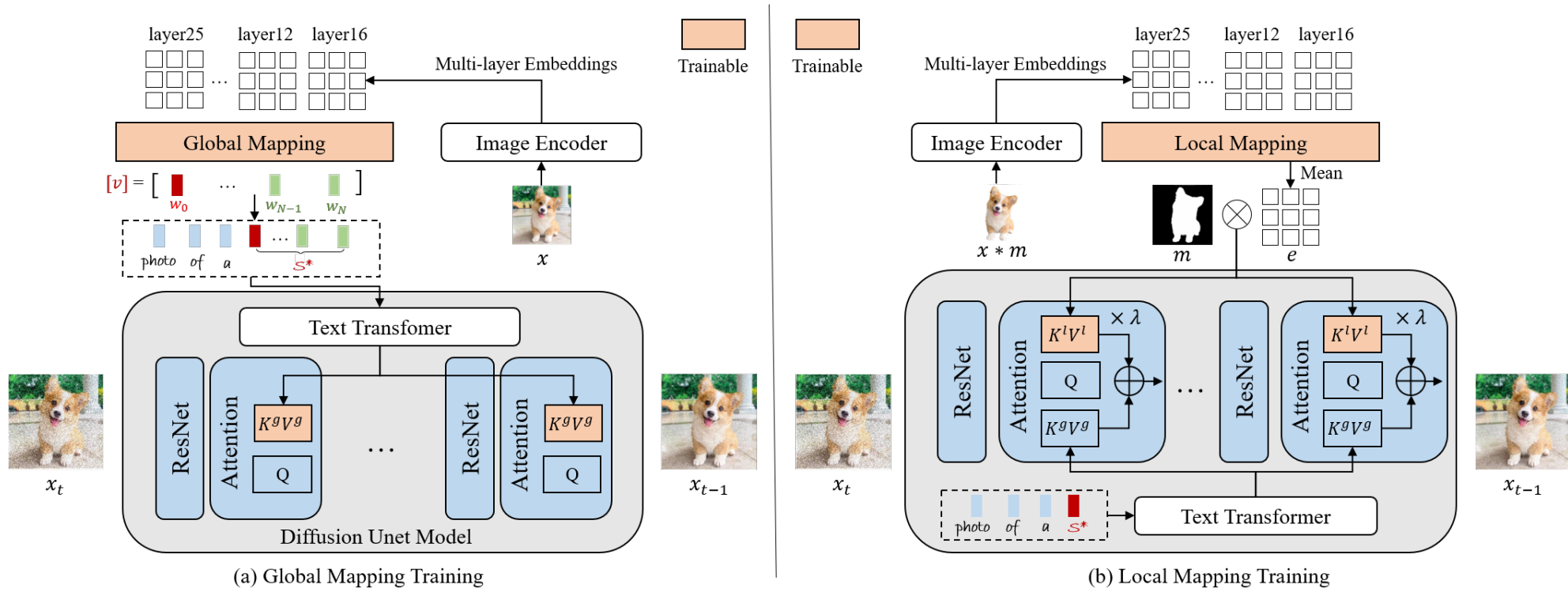
Tuning Encoder



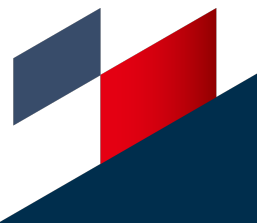
- Domain-Specific Encoder
- Weight Offsets



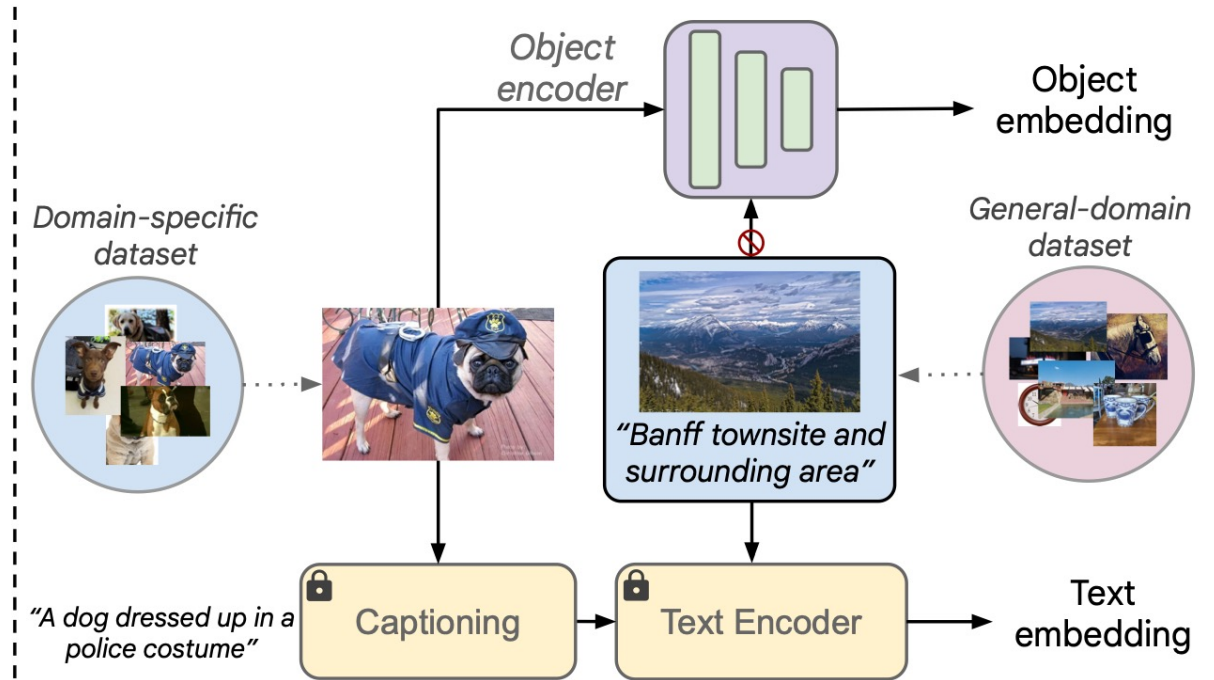
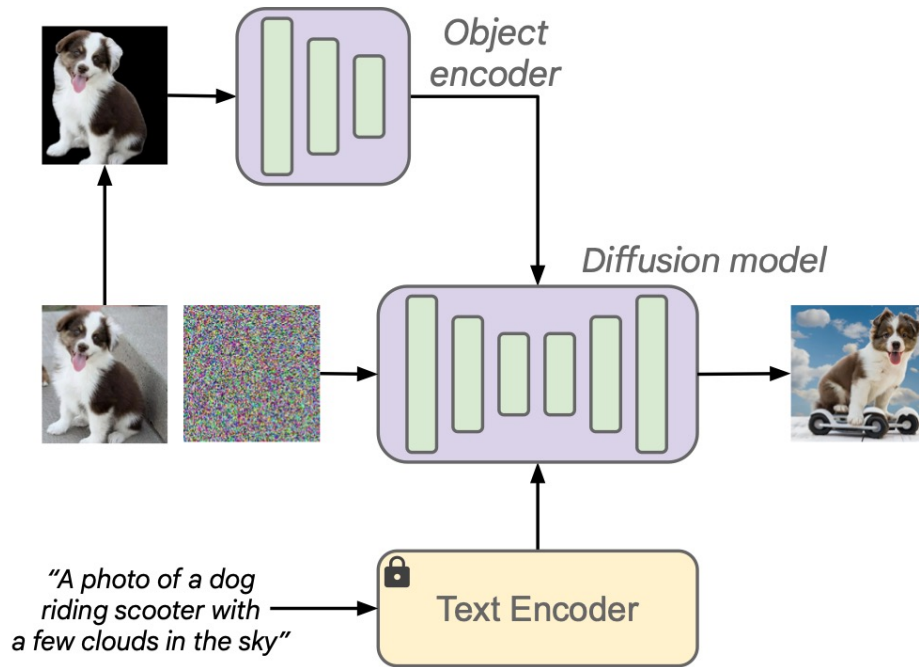
ELITE



- Global Mapping Network – Text Embeddings
- Local Mapping Network – Details



Taming Encoder



- Background Removal + Encoder
- Triplet Preparation Scheme

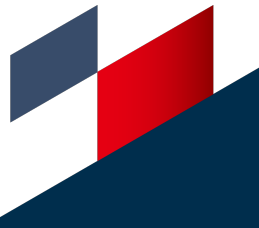


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 - ReVersion

ReVersion

Input

Exemplar Images



Output

Relation Prompt

<R>

represent the co-existing
relation in exemplar images

Application

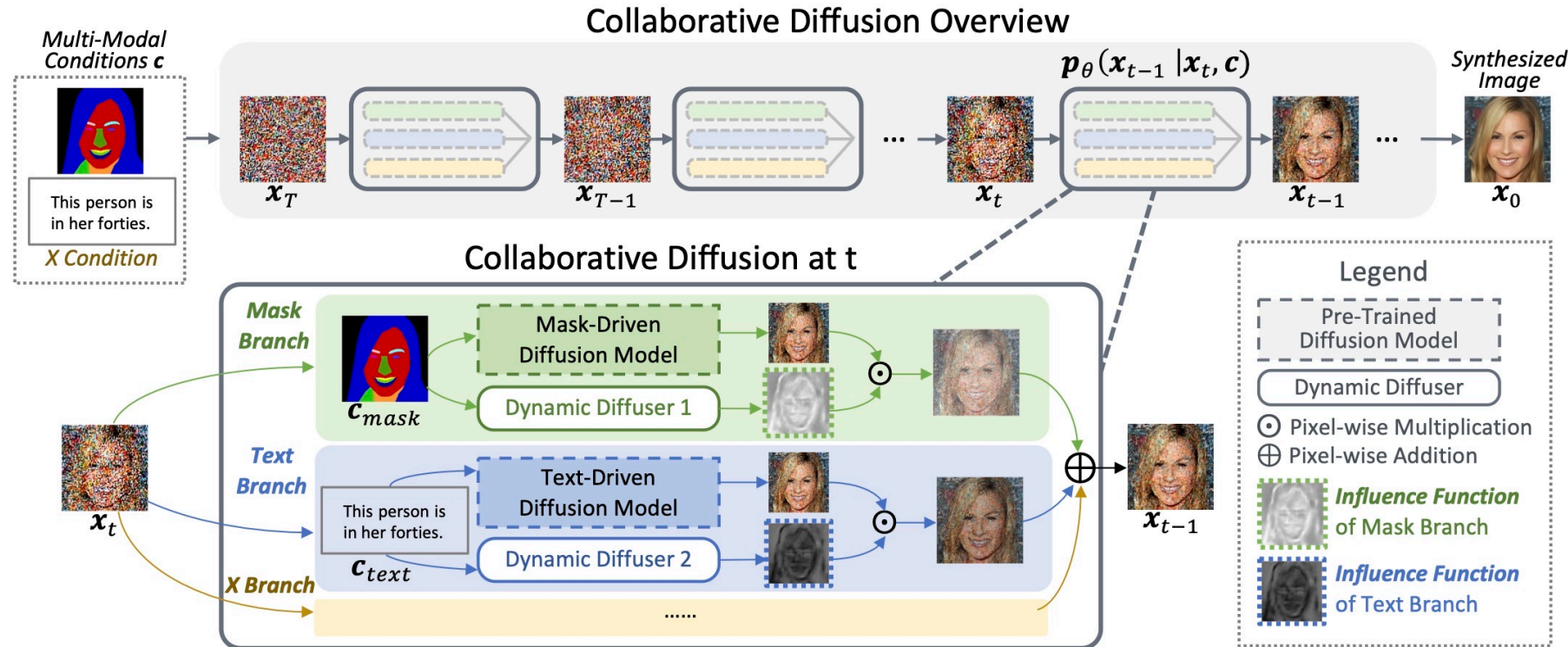
Relation-Specific Text-to-Image Synthesis



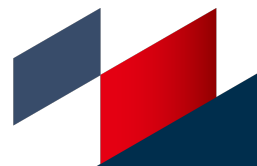
"~~Sphurabait~~ <R> ~~paper~~ bag"

"~~vegetable~~ is contained inside ~~paper~~ bag"

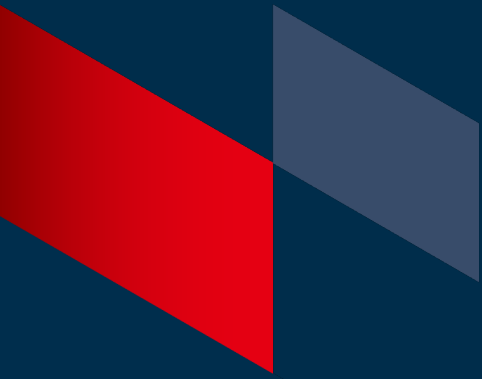
Collaborative Diffusion



- Use model collaboration to simultaneously accept different types of prompt: linguistic, visual



Text to Video Generation



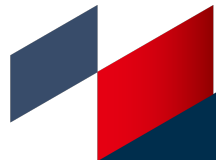
Text to Video Generation

- Auto-regressive methods
 - VideoGPT
 - TATS
 - Phenaki
- Diffusion models
 - Imagen Video
 - Gen1
 - Text2Performer



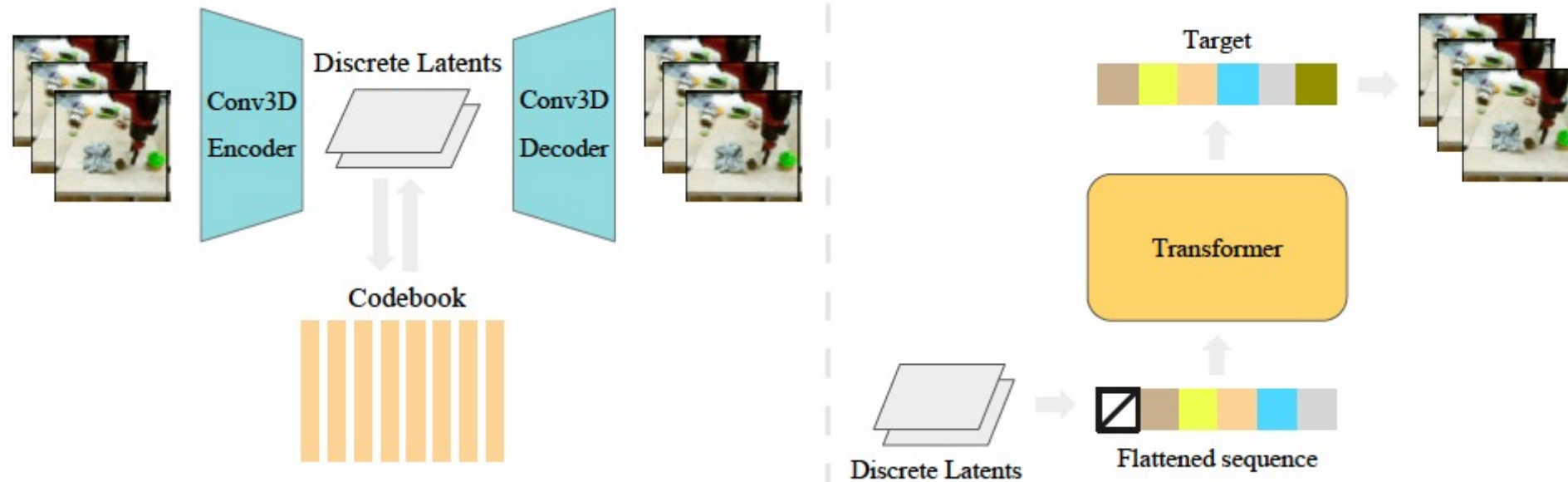
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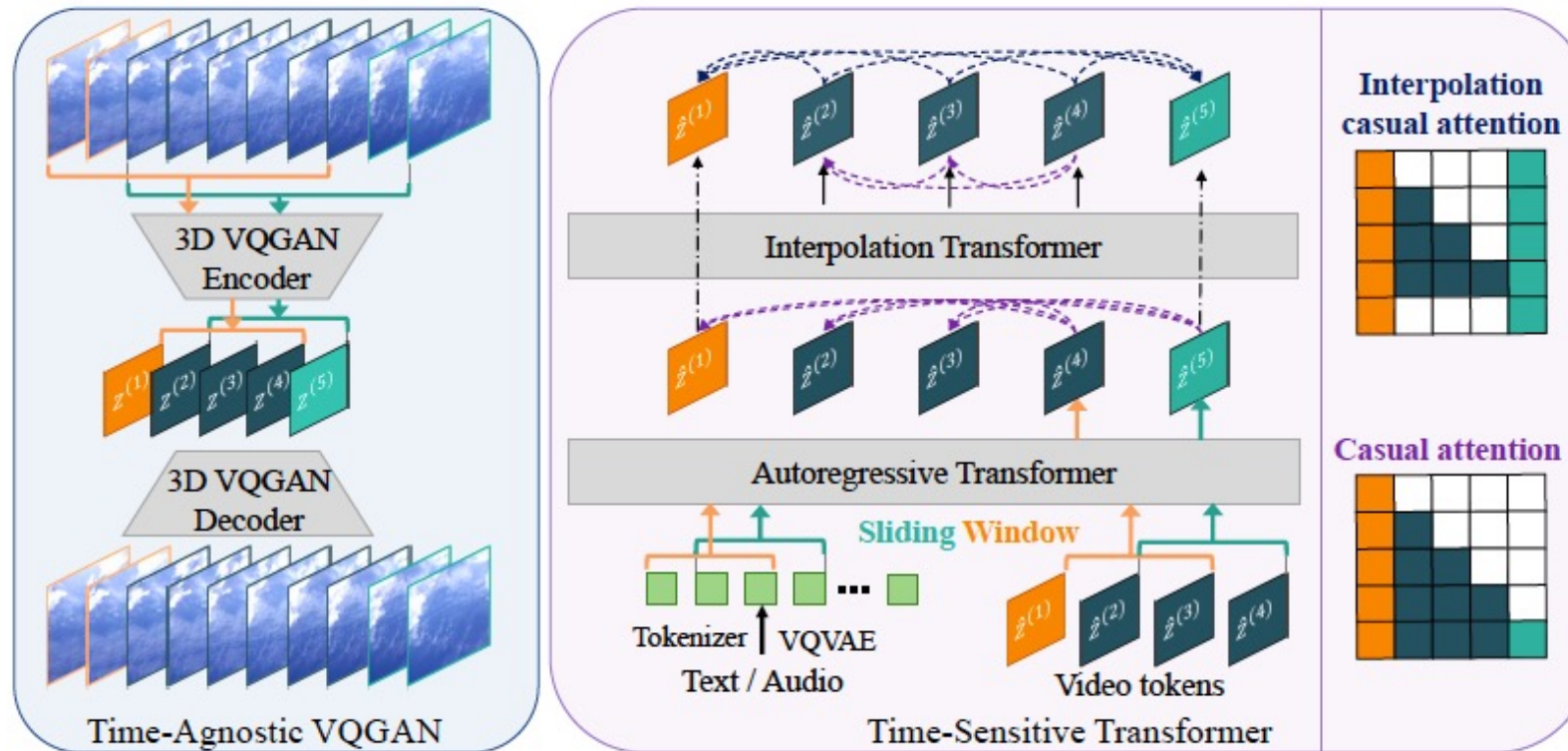
T2V: VideoGPT

- VQGAN: learn a set of discrete latent codes from raw pixels of the video frames.
- Transformer: learn a prior over the VQ-VAE latent codes.



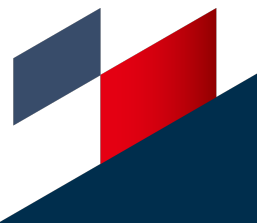
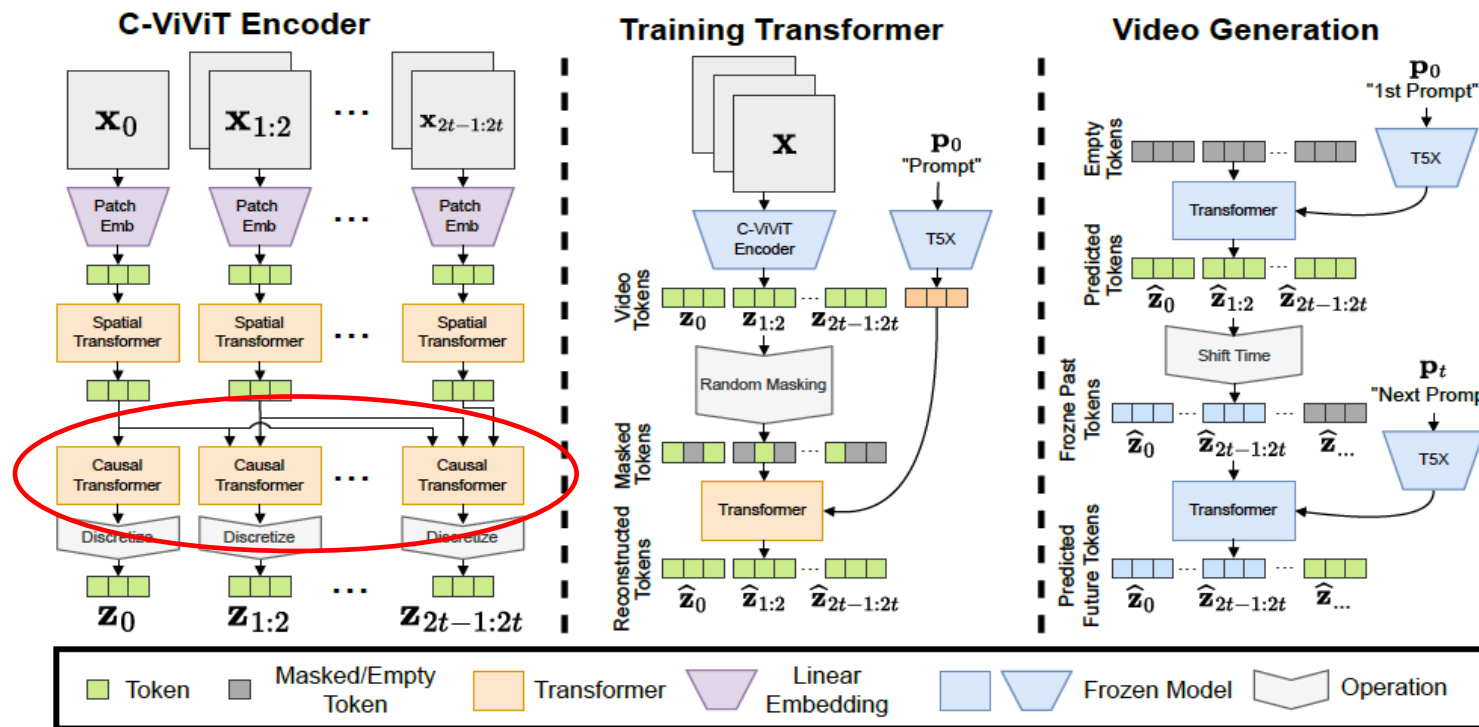
T2V: TATS

- 3D VQGAN: replacing 2D convolution operations with 3D convolutions for modeling videos.
- Transformer: the hierarchical transformer can model longer time dependence and delay the quality degradation.



T2V: Phenaki

- Encoder-decoder model: compress videos to discrete embeddings.
 - Causal attention makes the C-ViViT encoder autoregressive and enables it to handle a variable number of input frames.
- Transformer model: translate text embeddings to video tokens.



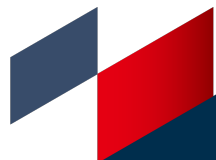
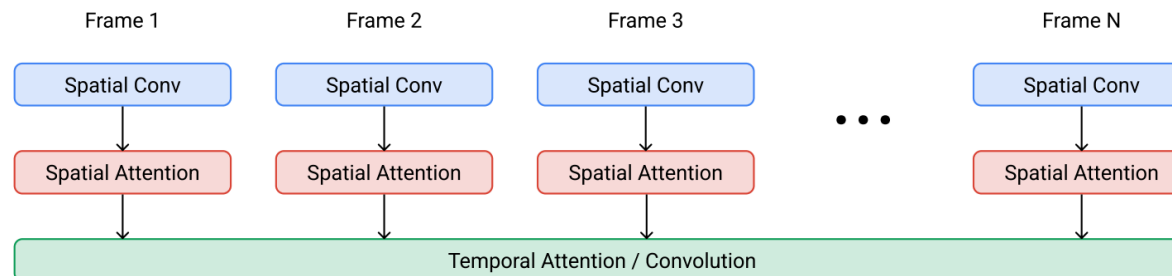
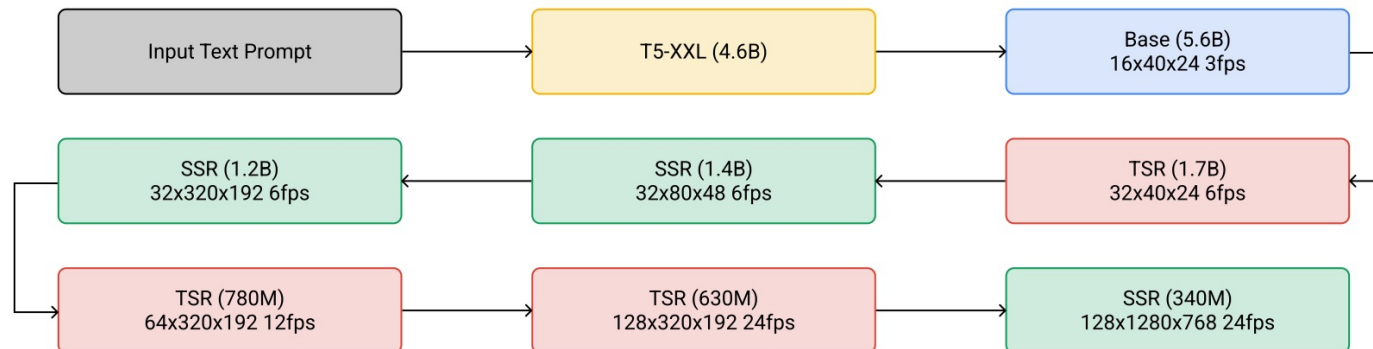
Text to Video Generation

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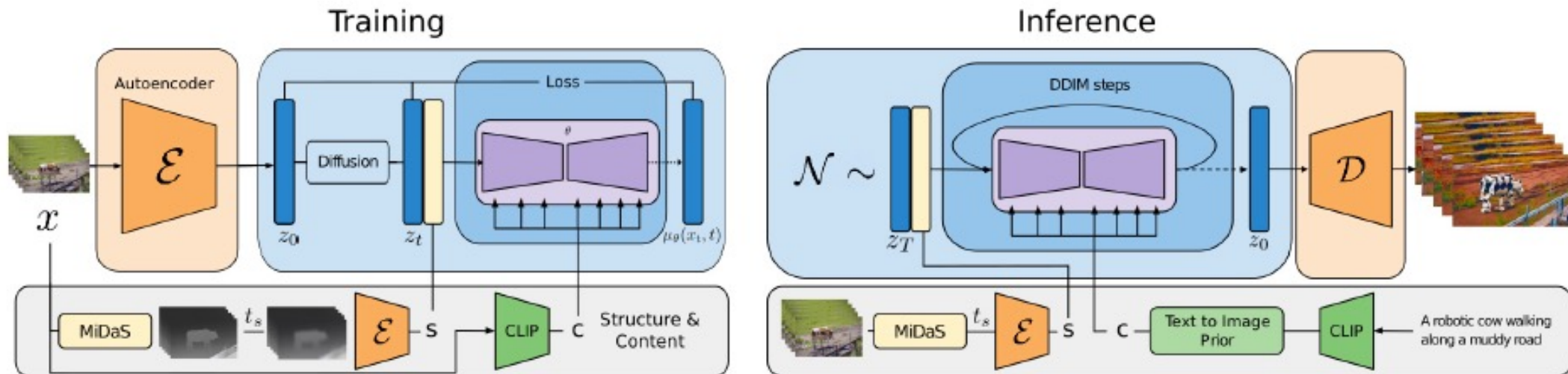
T2V: Imagen video

- Cascaded Diffusion Models.
 - 1 frozen text encoder, 1 base video diffusion model, 3 SSR (spatial super-resolution), and 3 TSR (temporal superresolution) models – for a total of 7 video diffusion models

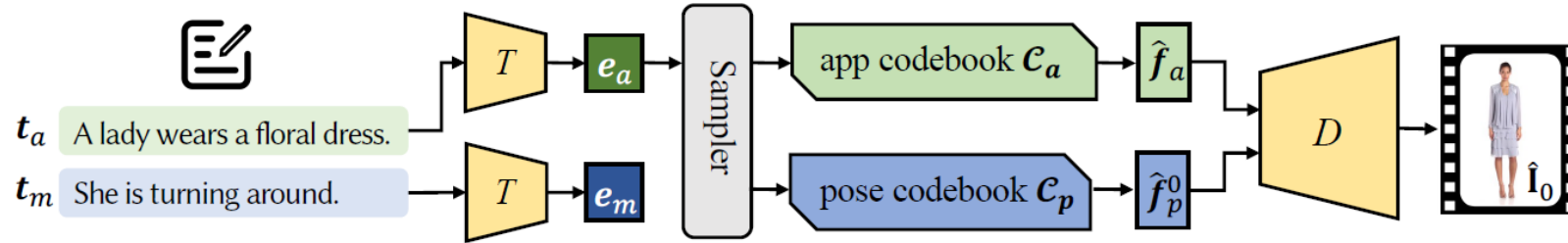


T2V: Gen1

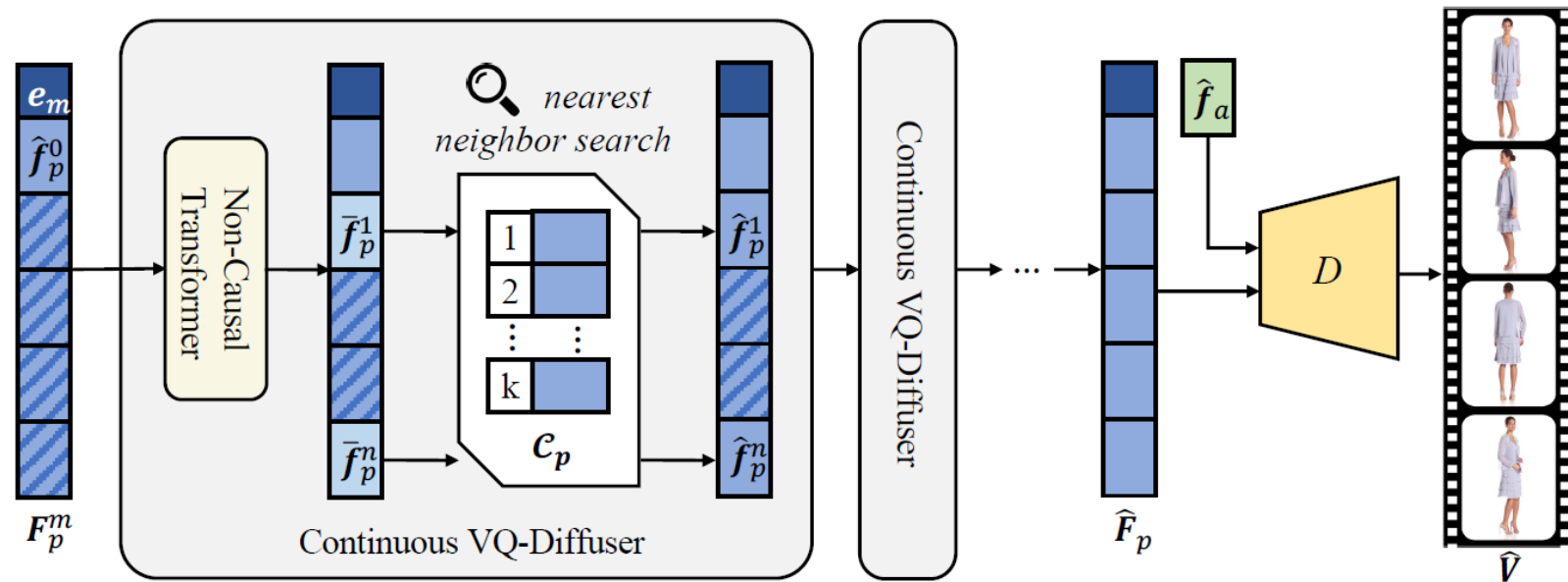
- Diffusion model: introduce temporal layers into a pre-trained image latent diffusion model
- Structure representation: utilize depth maps to provide control over structure and content fidelity.
- Content Representation: utilize CLIP to produce image (training) or text (inference) embeddings.



T2V: Text2Performer

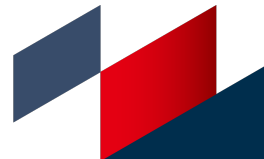


(b) Motion Sampling with Continuous VQ-Diffuser



Legend

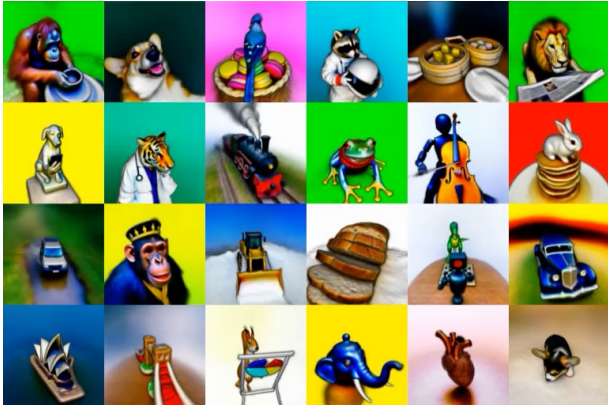






















- Text
- T Text encoder
- D VQ-VAE Decoder
- Sampler
- e Text embedding
- f Continuous embedding
- Masked continuous embedding
- c Codebook
- Appearance-related
- Motion-related



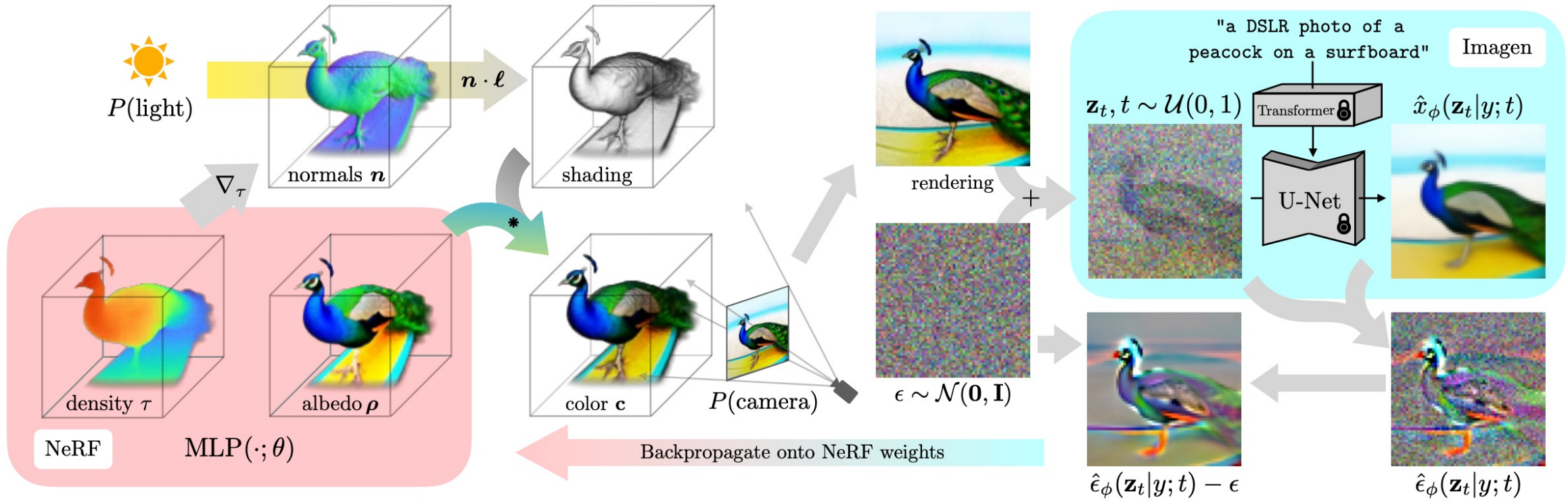
Text to 3D Generation



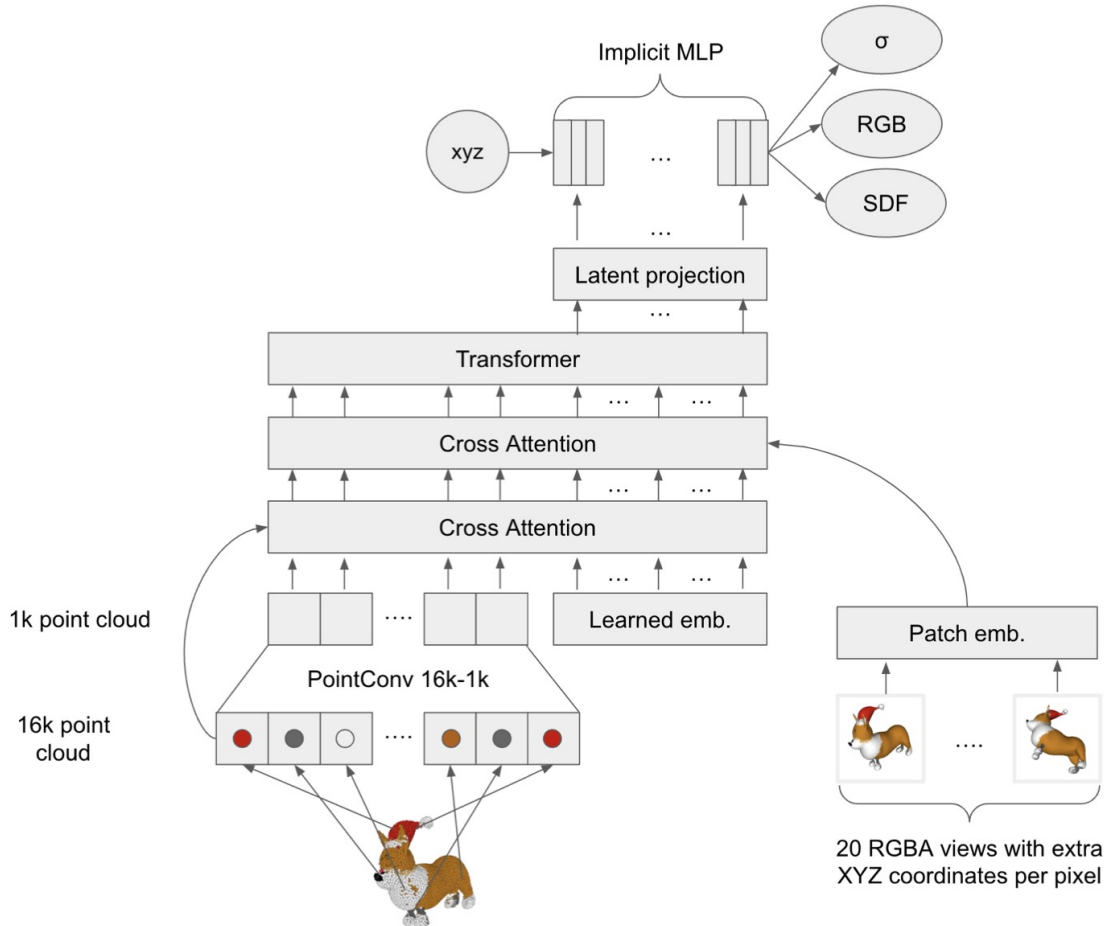
Overview

	Object	Human	Scene						
Leveraging 2D Prior from pretrained text-2D models	<p>DreamFusion</p> 	<p>AvatarCLIP</p> 	<p>Text2Room</p> 						
Supervised Training from text-3D paired data	<p>Shap-E</p> <table border="1"><tbody><tr><td> A chair that looks like an avocado</td><td> An airplane that looks like a banana</td><td> A spaceship</td></tr><tr><td> A birthday cupcake</td><td> A chair that looks like a tree</td><td> A green boot</td></tr></tbody></table>	 A chair that looks like an avocado	 An airplane that looks like a banana	 A spaceship	 A birthday cupcake	 A chair that looks like a tree	 A green boot	<p>Rodin</p> 	<p>Text2Light</p> 
 A chair that looks like an avocado	 An airplane that looks like a banana	 A spaceship							
 A birthday cupcake	 A chair that looks like a tree	 A green boot							

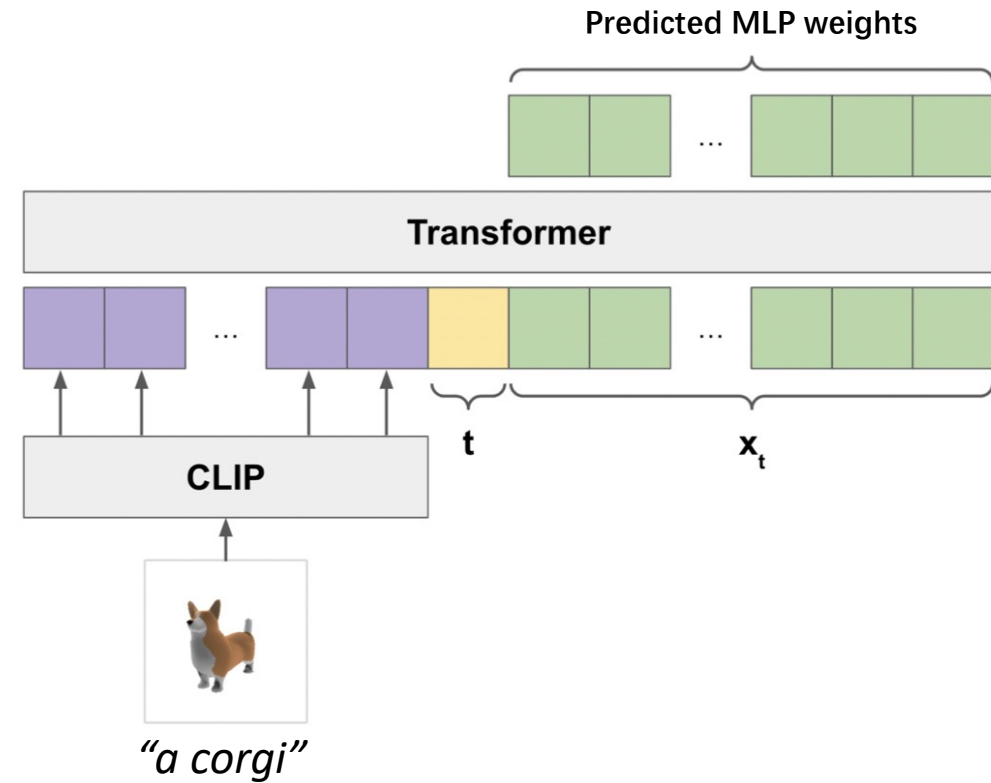
DreamFusion



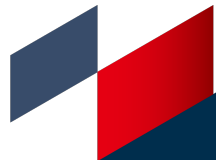
Shap-E



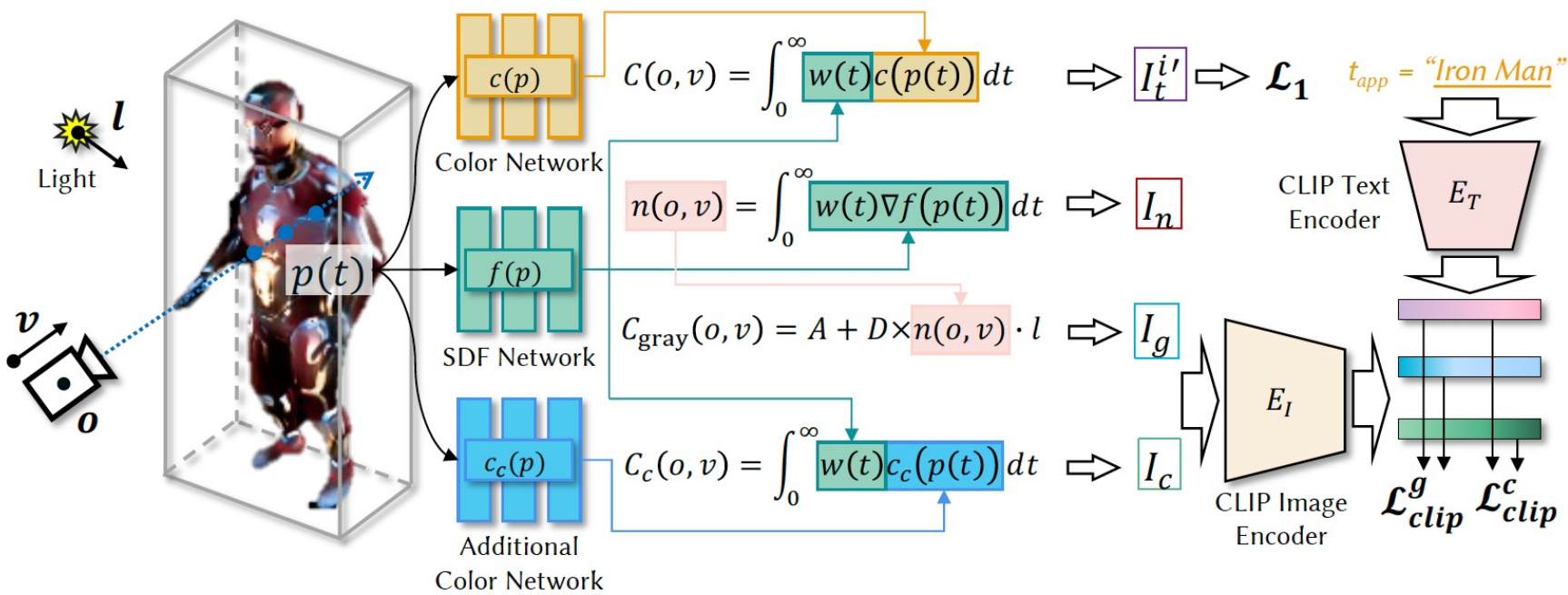
Step 1: Encode 3D Objects into Latent Space



Step 2: Latent Diffusion

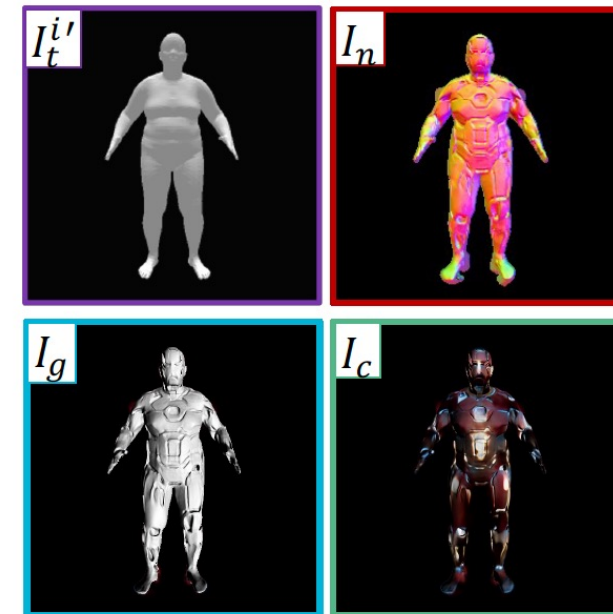


AvatarCLIP



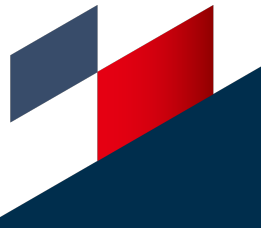
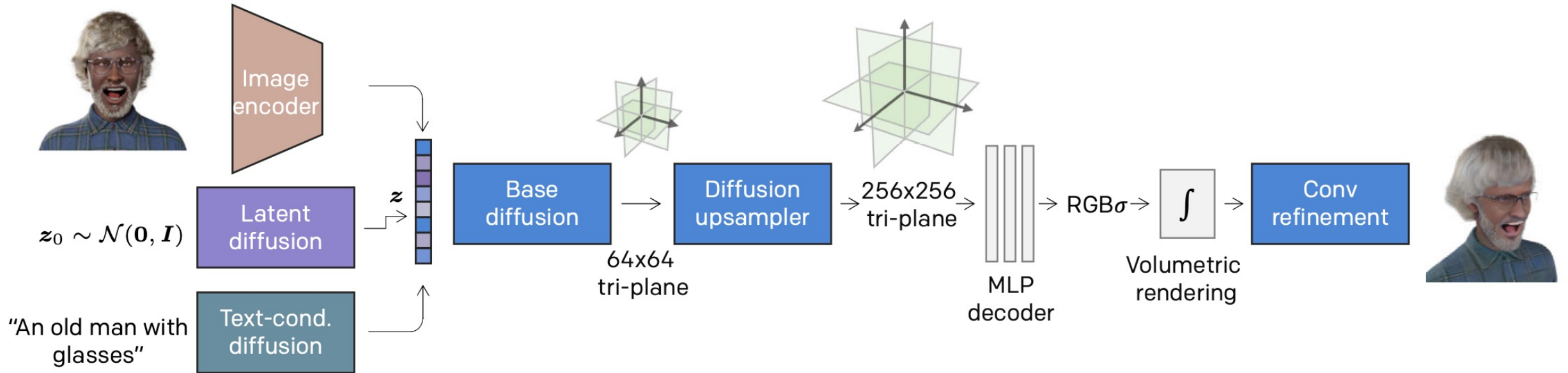
a) Rendering the Implicit 3D Avatar $N' = \{f(p), c(p), c_c(p)\}$

b) Optimization



Examples of Intermediate Results

Rodin



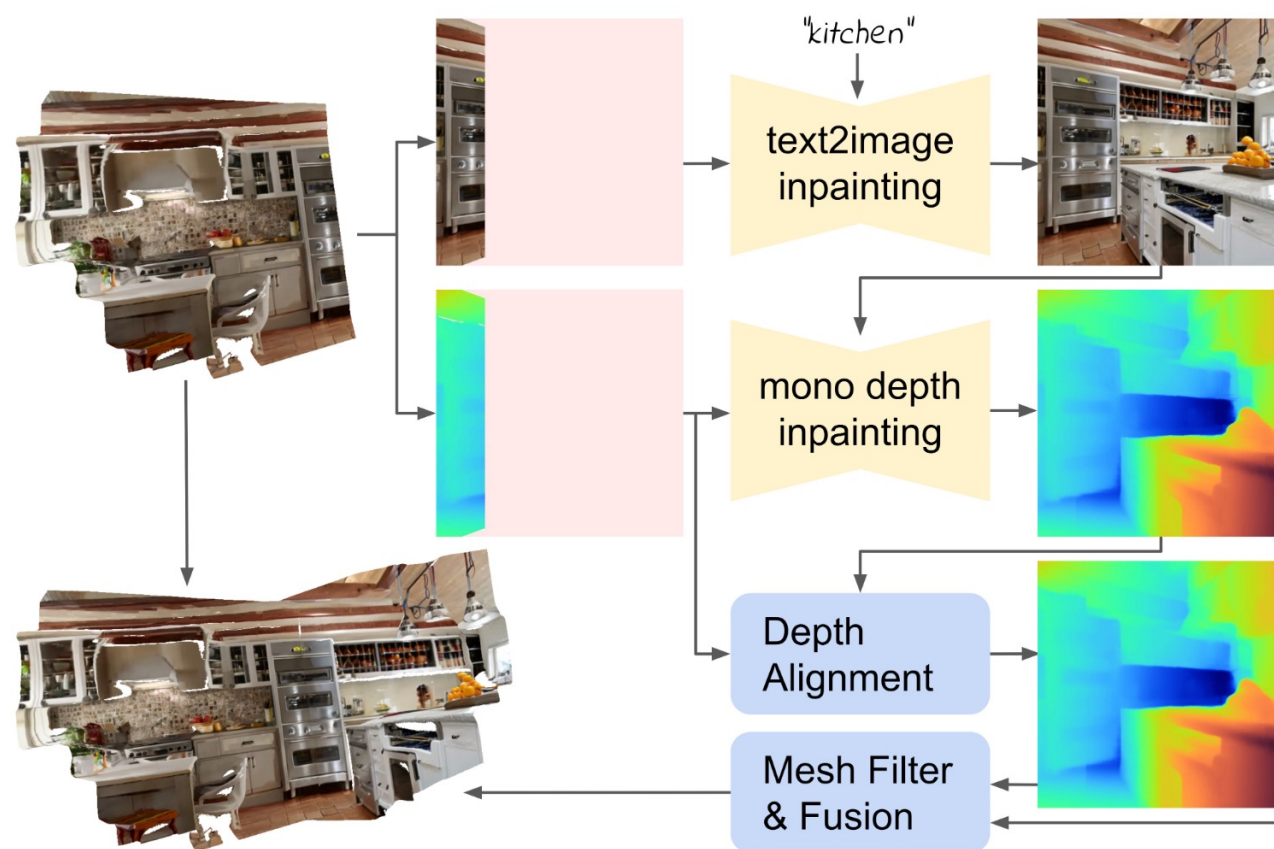
Text2Room: Extracting Textured 3D Meshes from 2D Text-to-Image Models



“Editorial Style Photo, Rustic Farmhouse, Living Room, Stone Fireplace, Wood, Leather, Wool”



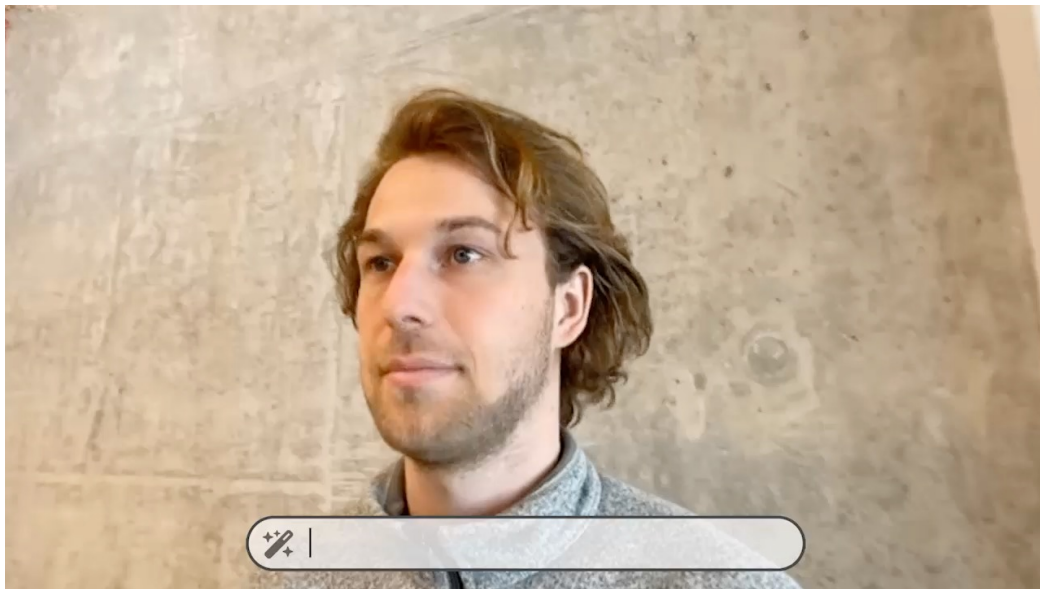
“A living room with a lit furnace, couch, and cozy curtains, bright lamps that make the room look well-lit.”



Text Prompts -> 3D Scenes
Optimization based



Instruct-NeRF2NeRF: Editing 3D Scenes with Instructions



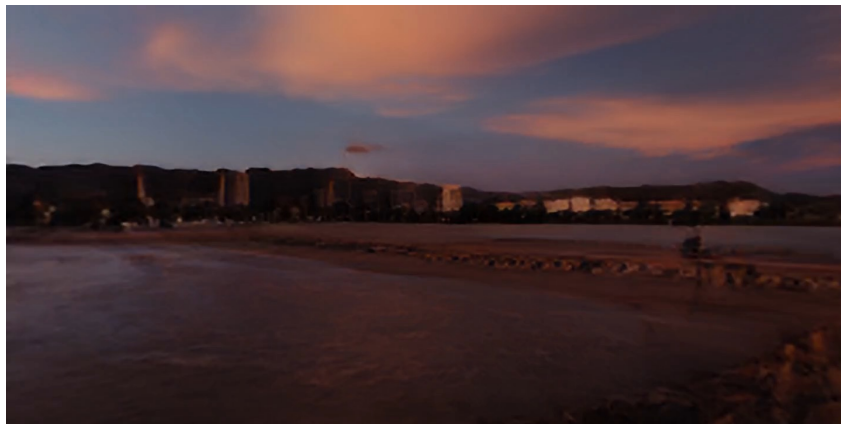
Edit 3D Scenes via Instructions



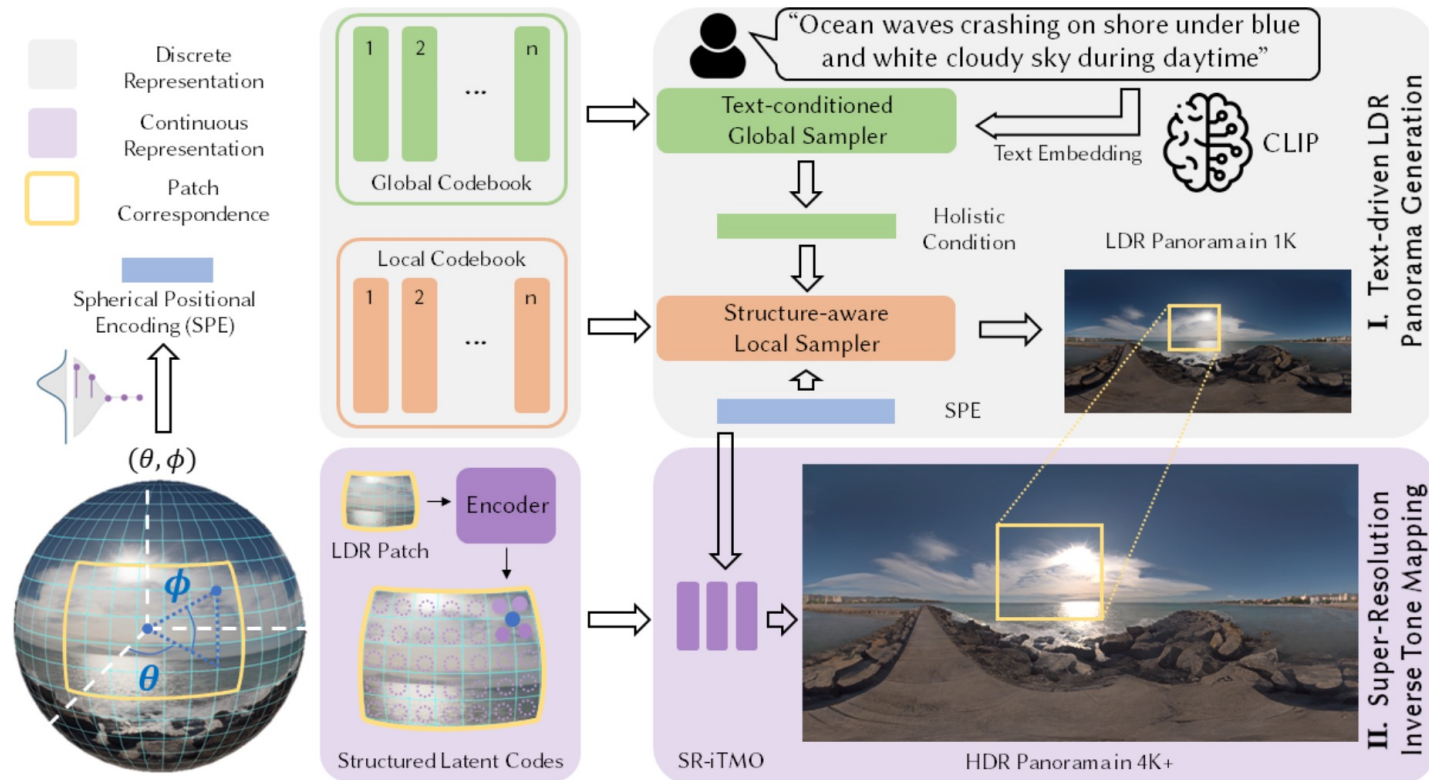
Text Prompts + Instruction Tuning -> 3D Scenes
Optimization based



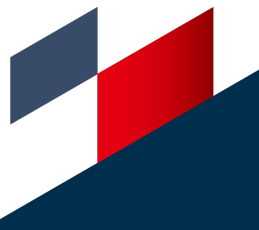
Text2Light: Zero-shot Text-driven HDR Panorama Generation



“Sunset by the Ocean”



Text Prompts -> Panoramic 3D Scenes
Feed Forward Generation



Future work

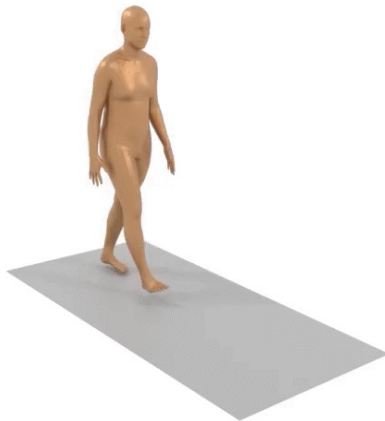
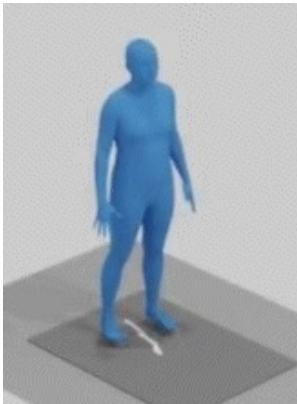
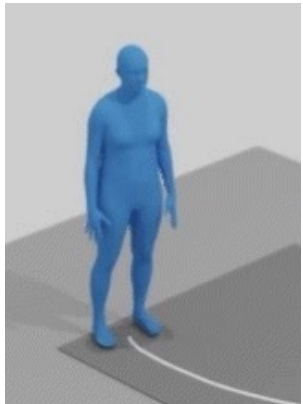
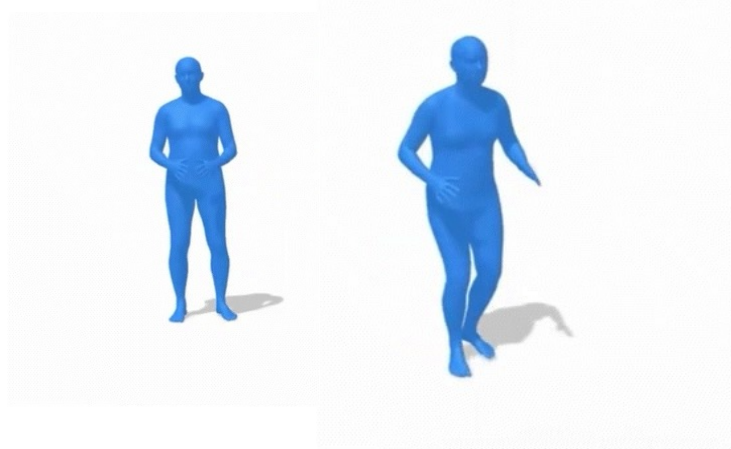
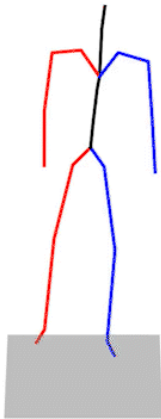
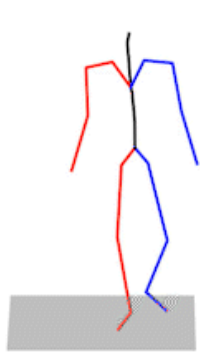
- **Faster Generation:**
 - Per-scene-optimization is time consuming.
- **Higher Quality:**
 - The resolution is limited by the resolution of 2D model.
 - Super high guidance weight leads to over-saturation, over-smoothing results.
- **More Efficient 3D Representation**
 - Directly learning from 3D data is expensive.



Text to 4D Generation



Text-to-4D Generation

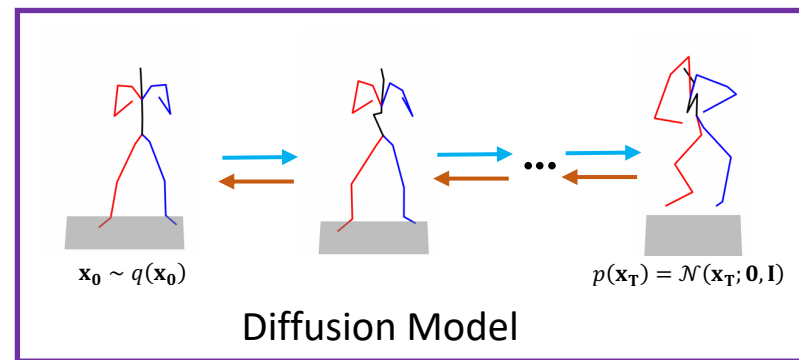
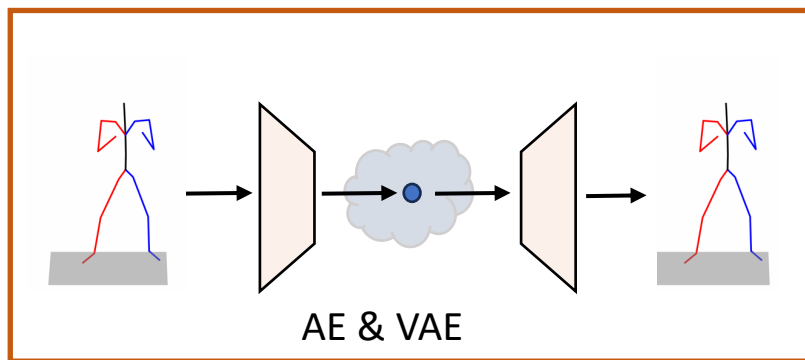
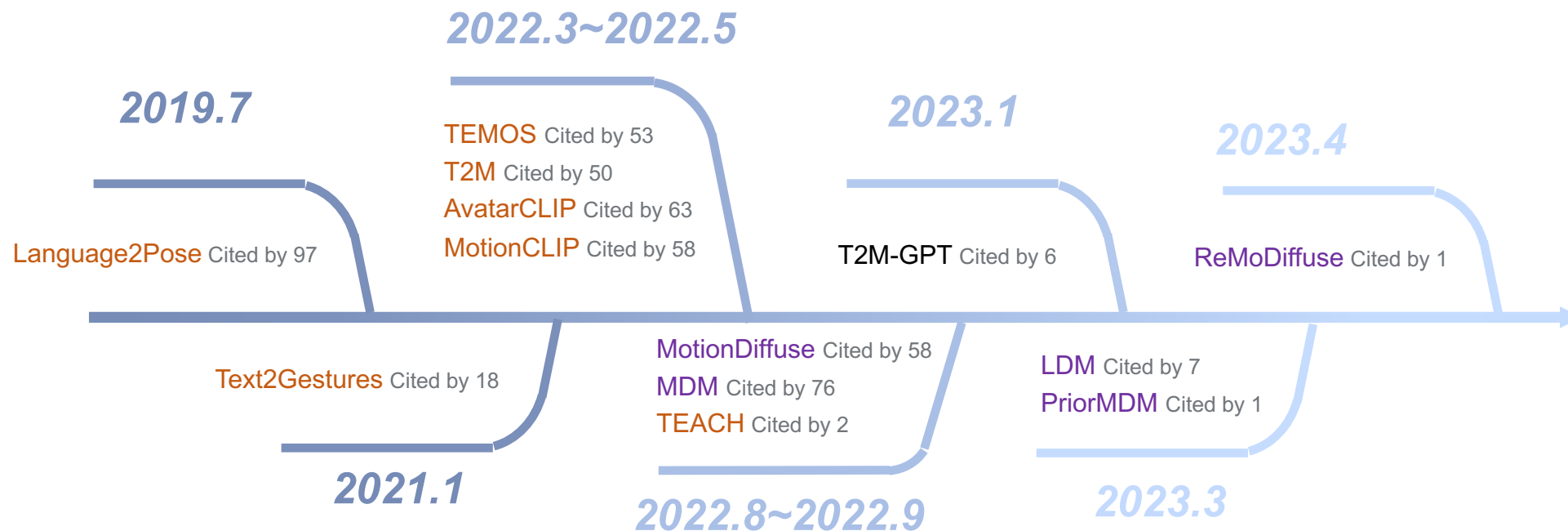


Motion generation

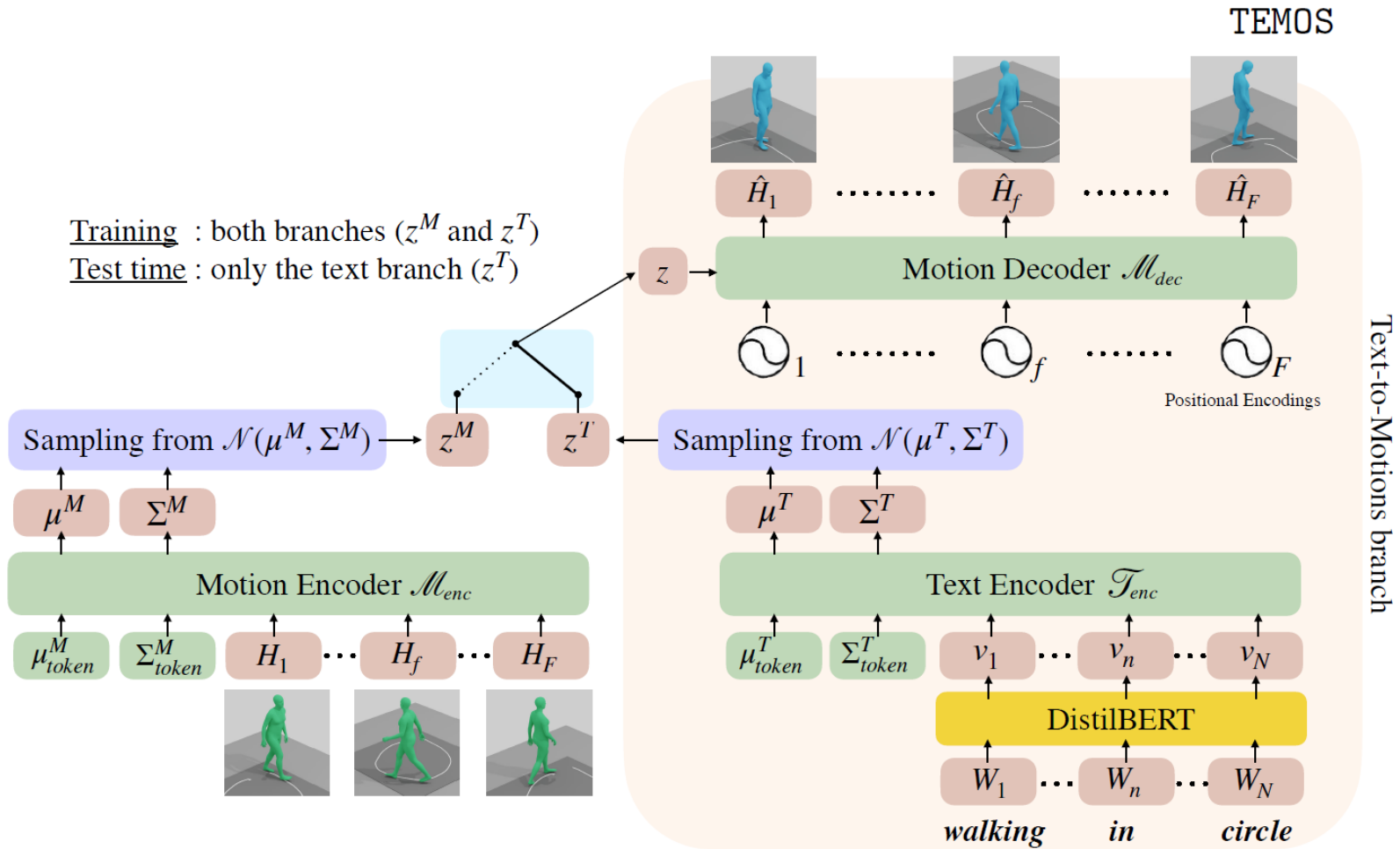


4D scene generation

Human Motion Generation

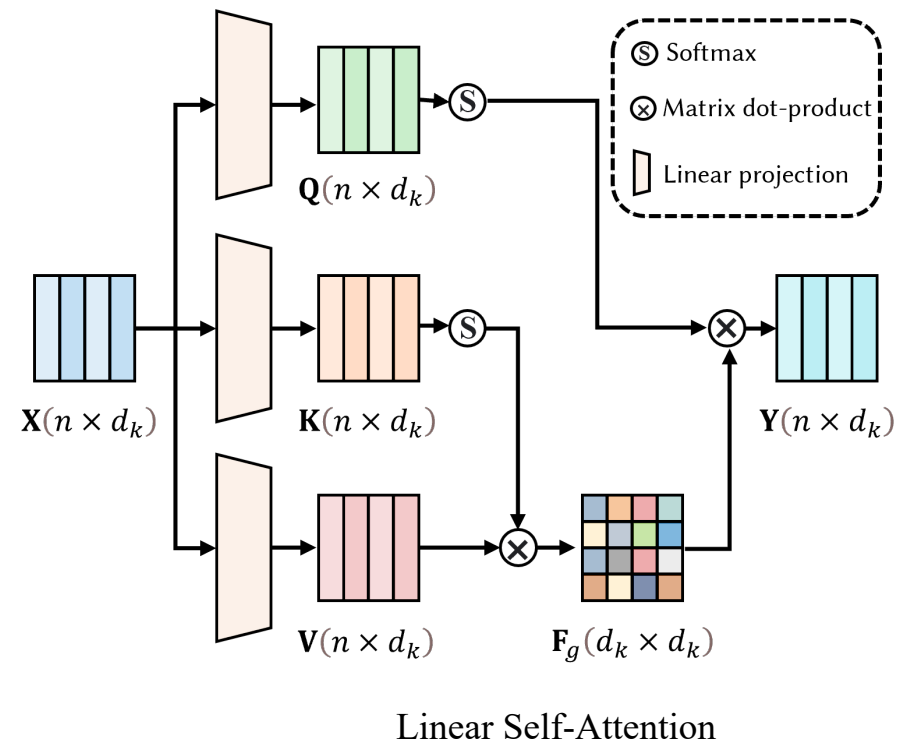
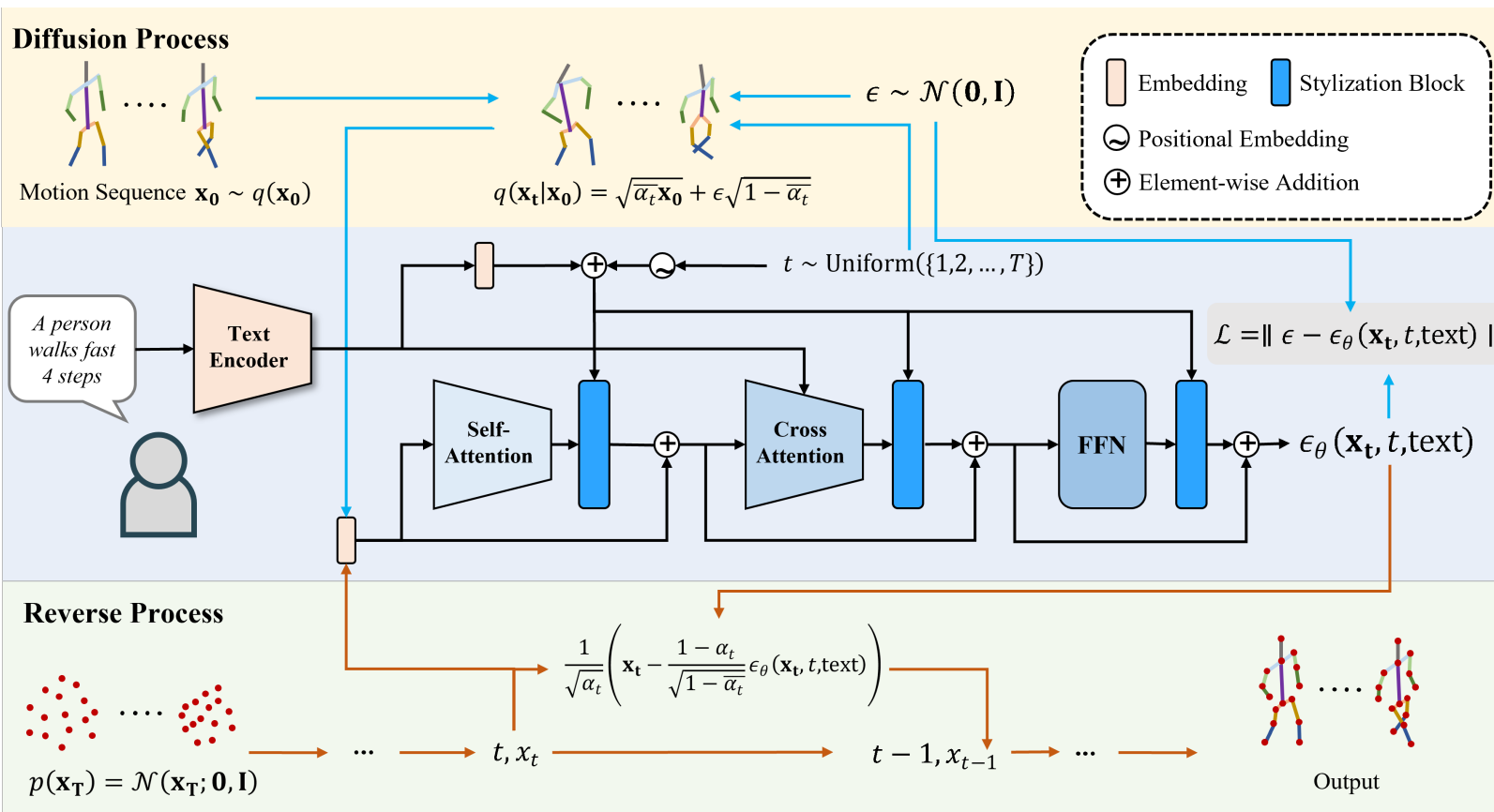


TEMOS

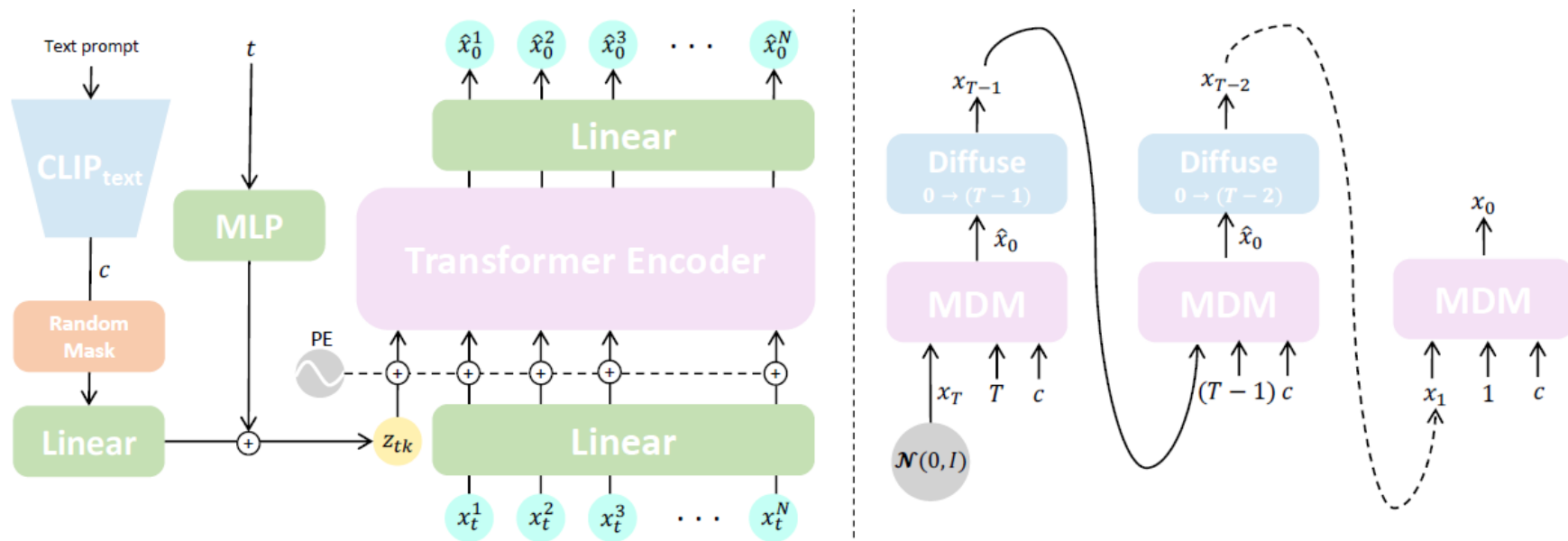


$$\mathcal{L} = L_1(H, \hat{H}^M) + L_1(H, \hat{H}^T) + KL(\phi^T, \phi^M) + KL(\phi^M, \phi^T) + KL(\phi^T, \psi) + KL(\phi^M, \psi)$$

MotionDiffuse



MDM



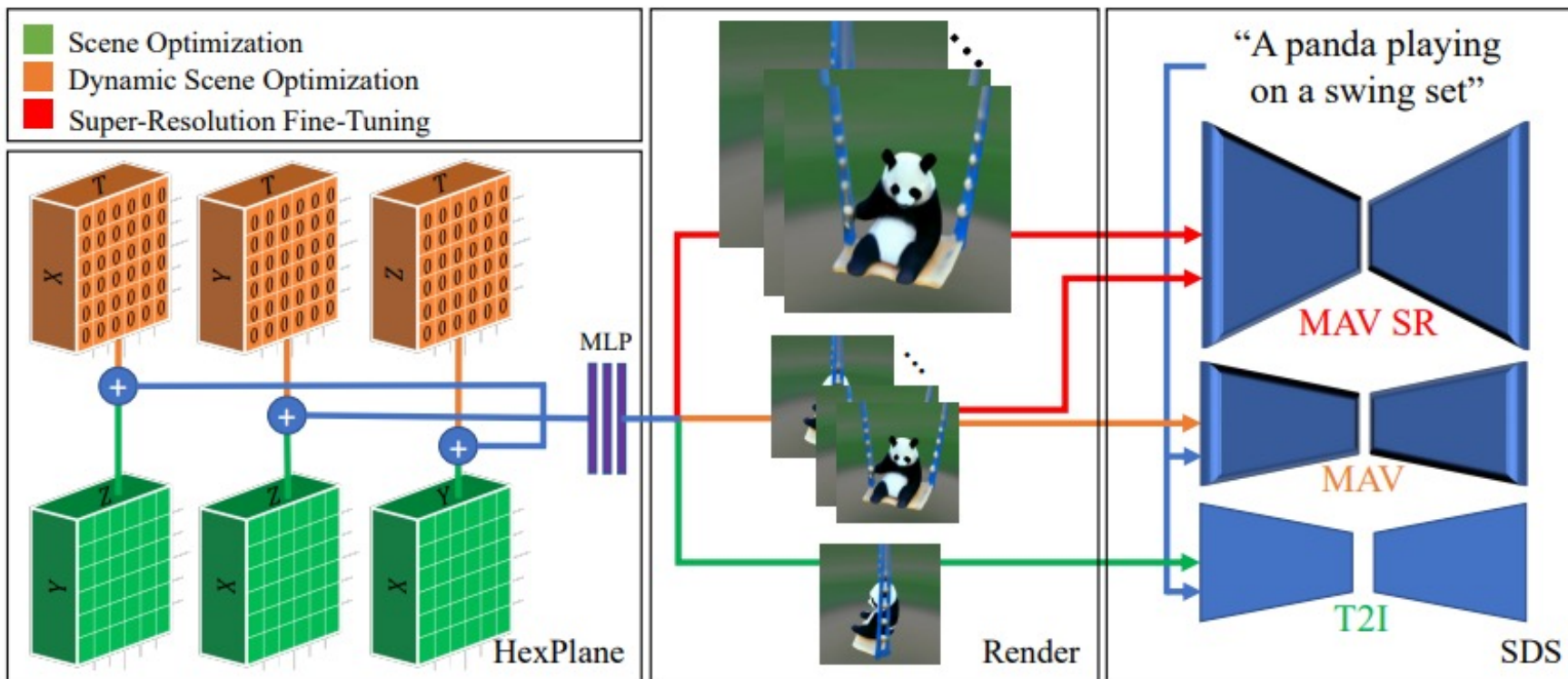
Geometric Loss

$$\mathcal{L}_{\text{pos}} = \frac{1}{N} \sum_{i=1}^N \|FK(x_0^i) - FK(\hat{x}_0^i)\|_2^2$$

$$\mathcal{L}_{\text{foot}} = \frac{1}{N-1} \sum_{i=1}^{N-1} \|(FK(\hat{x}_0^{i+1}) - FK(\hat{x}_0^i)) \cdot f_i\|_2^2$$

$$\mathcal{L}_{\text{vel}} = \frac{1}{N-1} \sum_{i=1}^{N-1} \|(x_0^{i+1} - x_0^i) - (\hat{x}_0^{i+1} - \hat{x}_0^i)\|_2^2$$

4D Scene Generation – MAV3D



4D Scene Representation

$$[P_{xy}^{XYR_1} + P_{zt}^{ZTR_1}; P_{xz}^{XZR_2} + P_{yt}^{YTR_2}; P_{yz}^{YZR_3} + P_{yz}^{XTR_3}]$$

Dynamic Scene Optimization

$$\nabla_{\theta} \mathcal{L}_{SDS-T} = E_{\sigma, \epsilon} \left[w(\sigma) (\hat{\epsilon}(V_{(\bar{\theta}, \sigma, \epsilon)} | y, \sigma) - \epsilon) \frac{\partial V_{\theta}}{\partial \theta} \right]$$

Future Direction

- 1. More Customized Generation**
- 2. More Dynamic Modeling**
- 3. More Fine-Grained Alignment**

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